

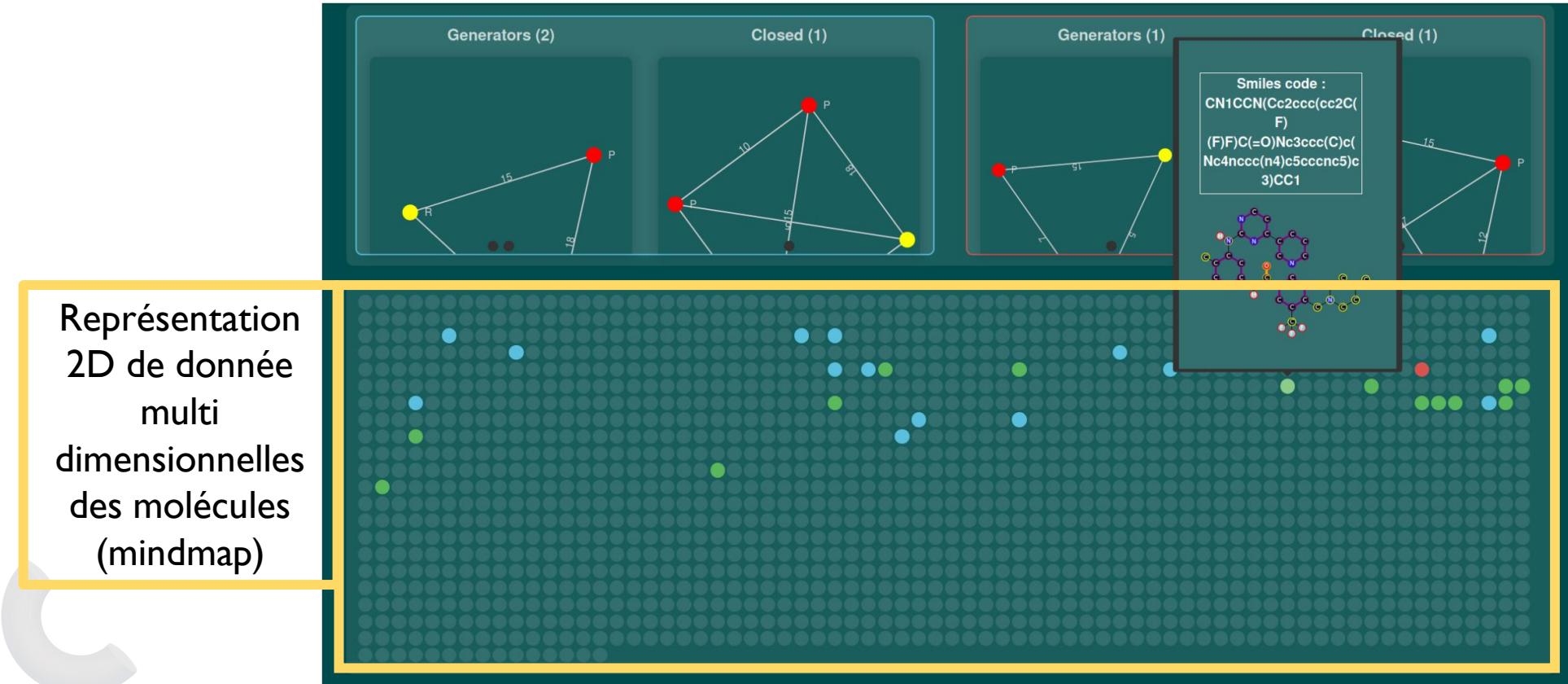
Visualisation compacte de données multidimensionnelles

David Auber

En collaboration avec:

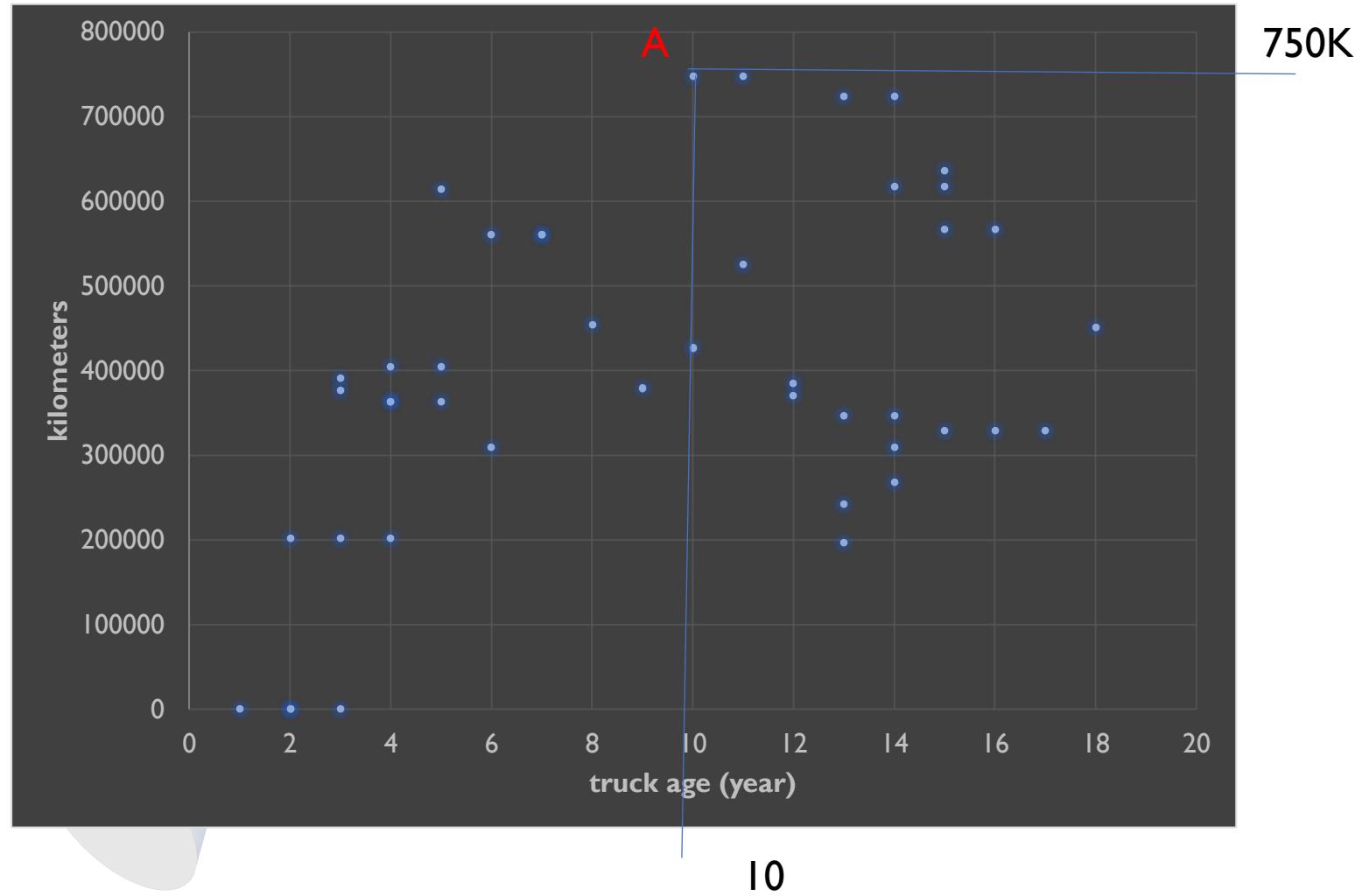
Adrien Halnaut, Romain Giot et Romain Bourqui

Données multidimensionnel dans InvolvD



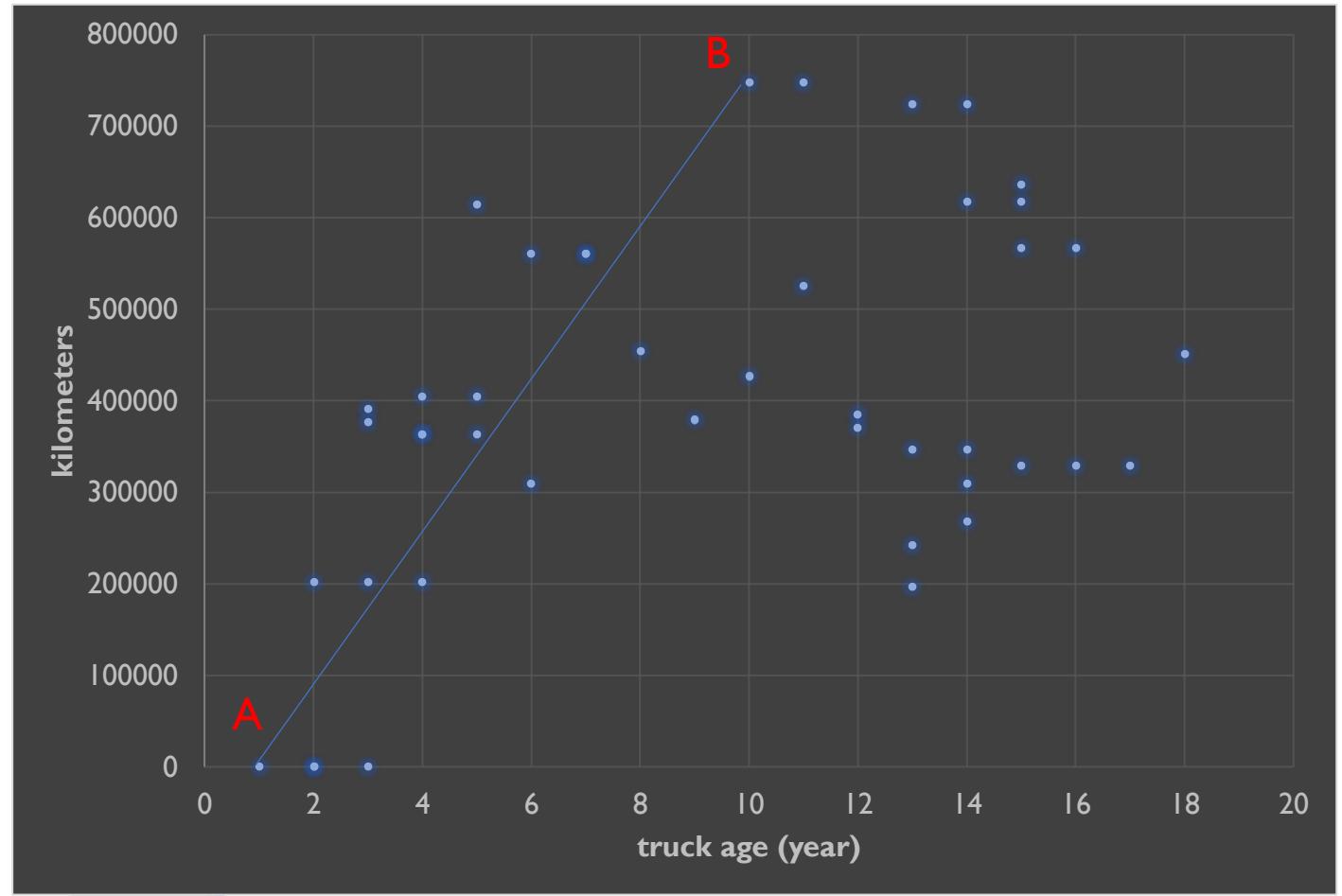
What are we looking for ?

- Read values of data points ?
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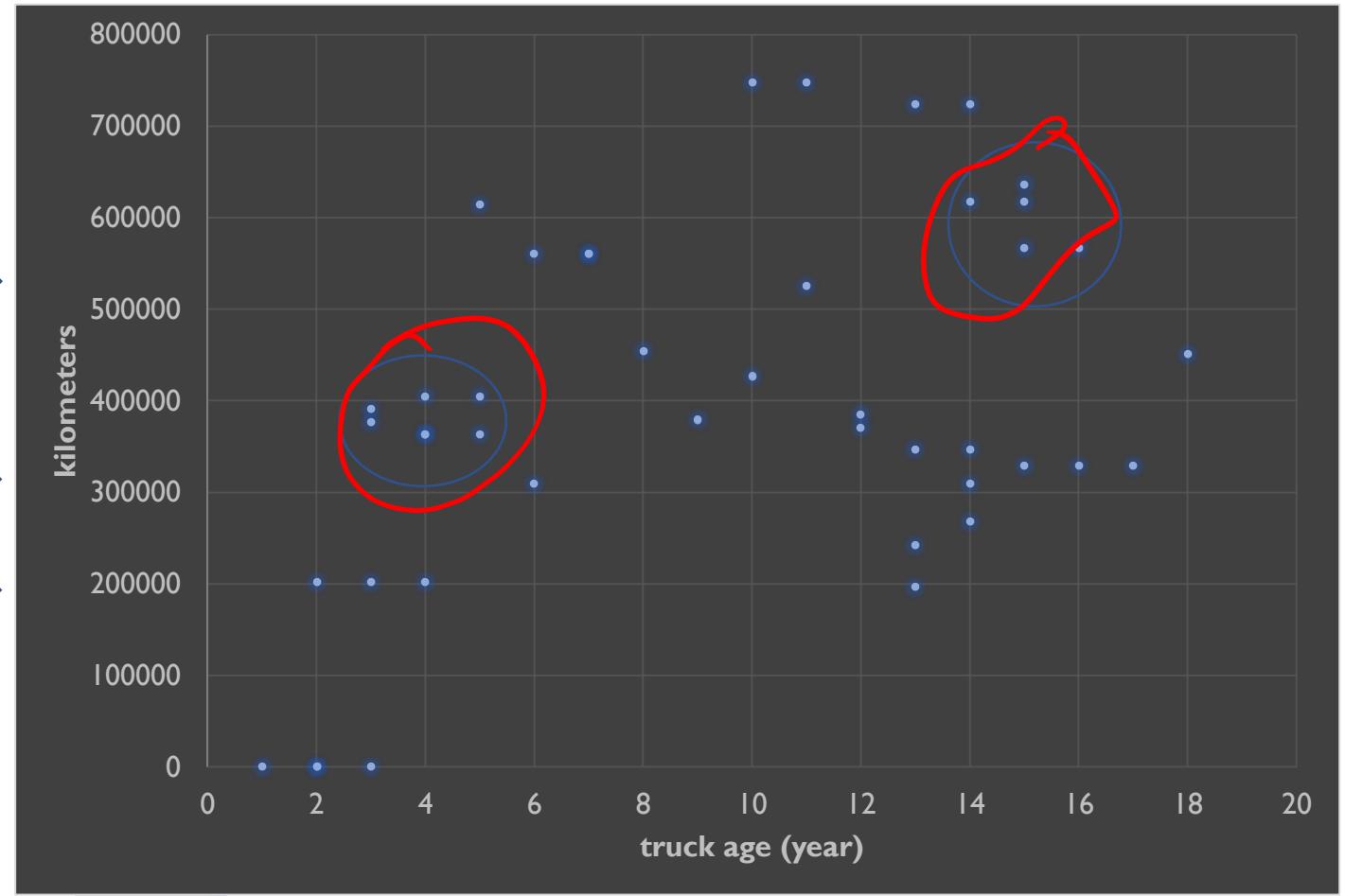
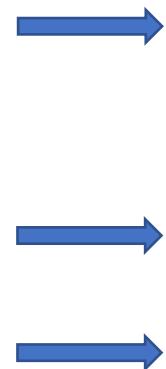
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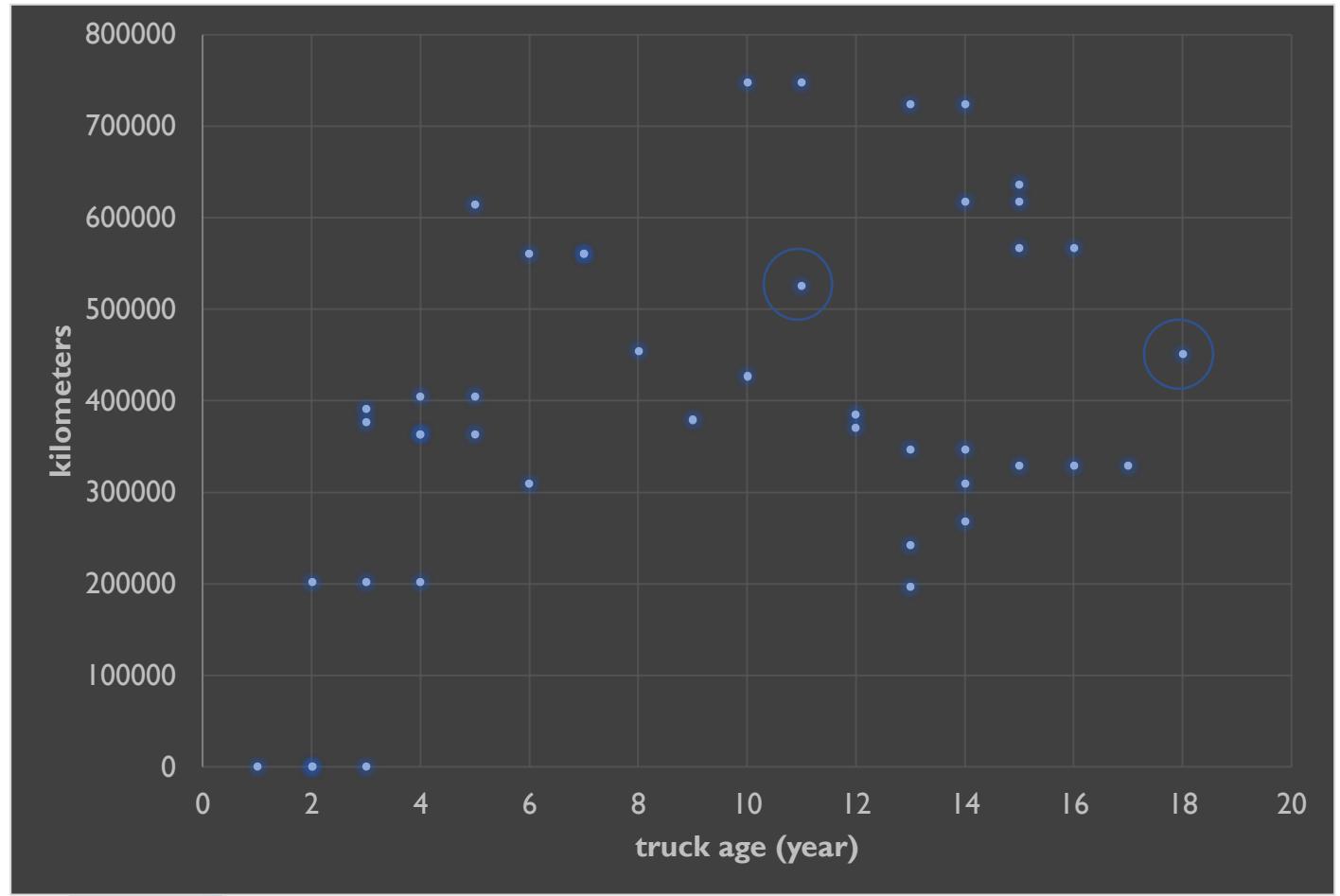
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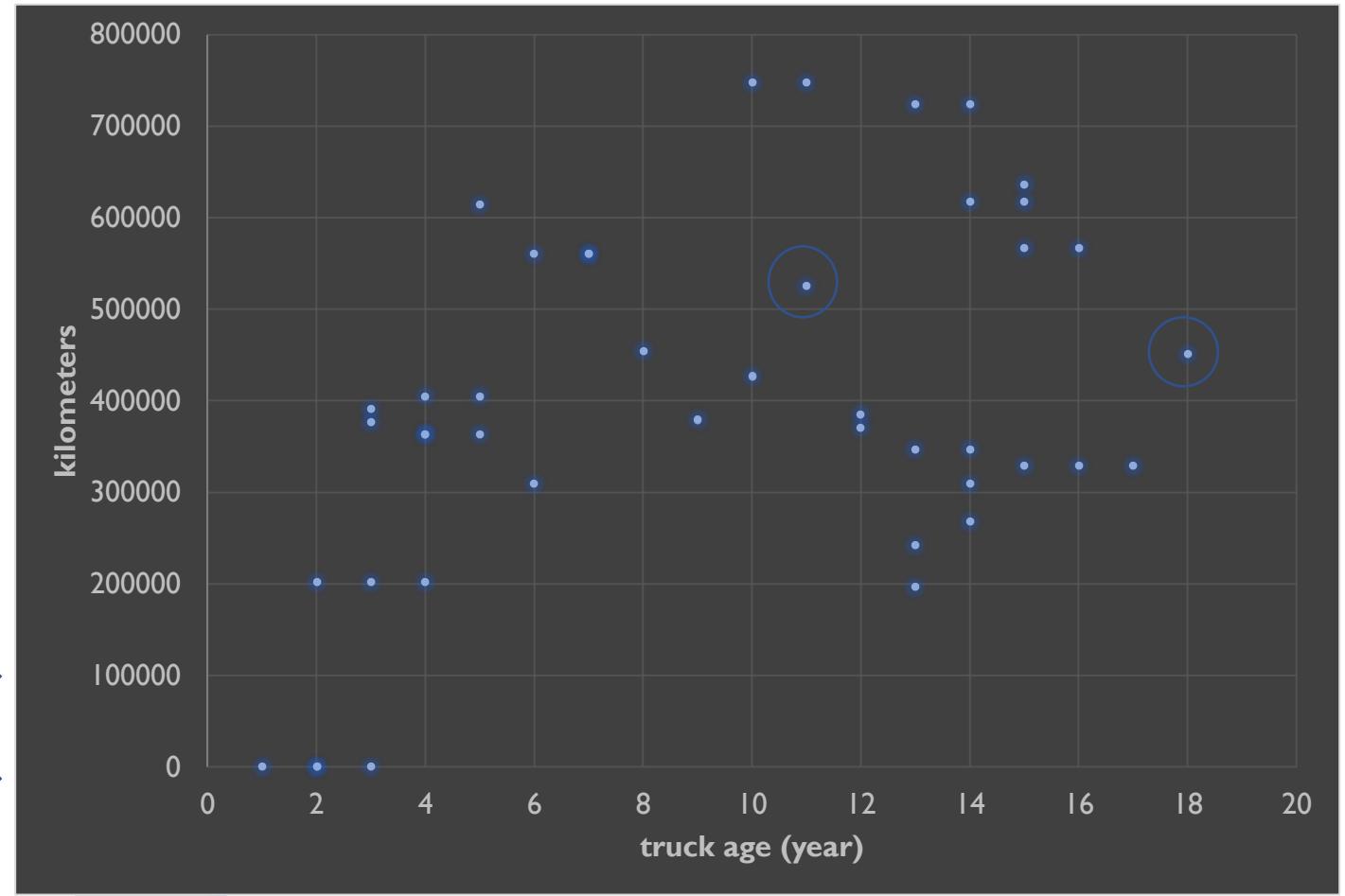
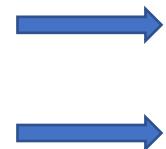
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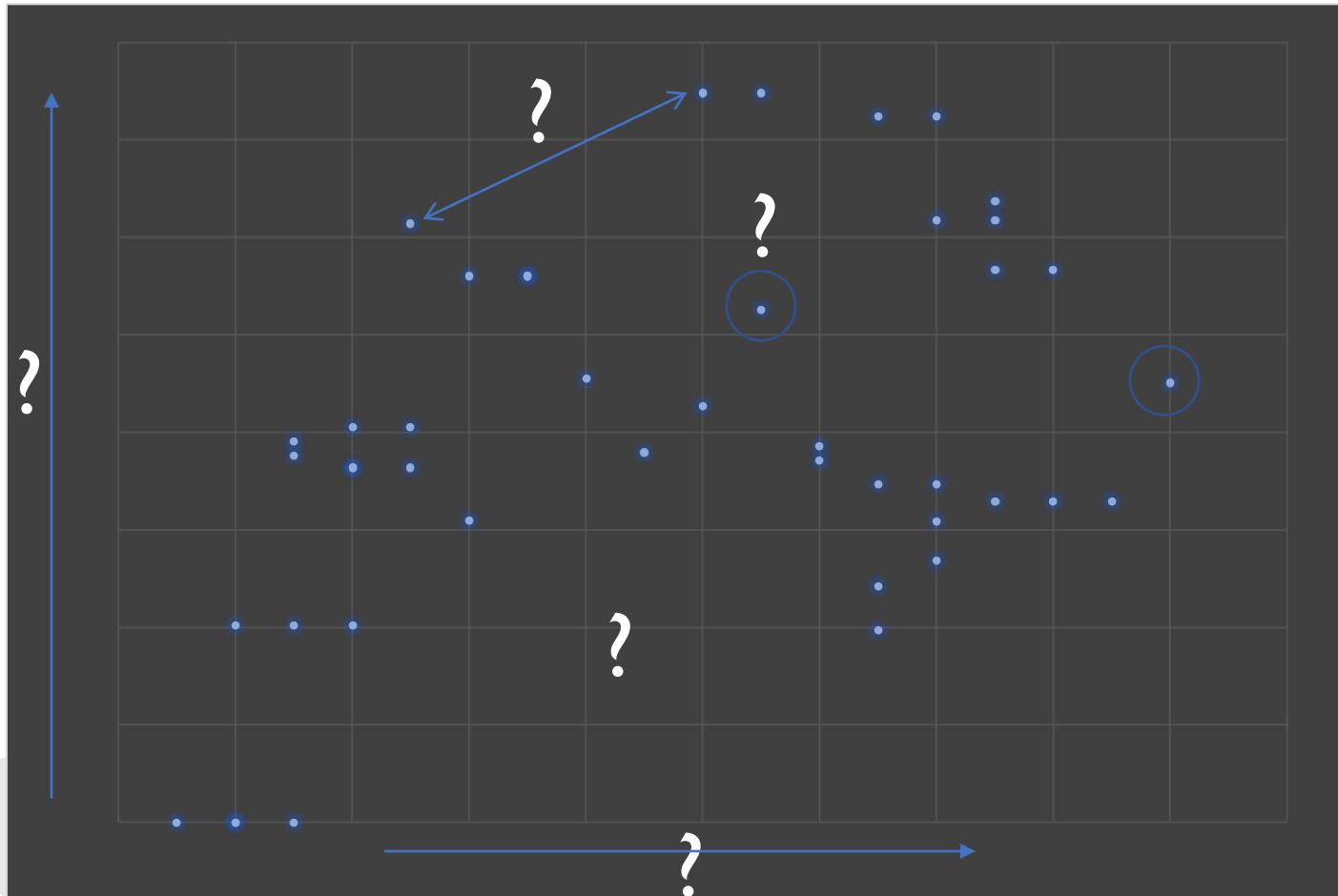
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Curse of dimensionality

3	4	2	1	9	5	6	2	1	8
8	9	1	2	5	0	0	6	6	4
6	7	0	1	6	3	6	3	7	0
3	7	7	9	4	6	6	1	8	2
2	9	3	4	3	9	8	7	2	5
1	5	9	8	3	6	5	7	2	3
9	3	1	9	1	5	8	0	8	4
5	6	2	6	8	5	8	8	9	9
3	7	7	0	9	4	8	5	4	3
7	9	6	4	7	0	6	9	2	3

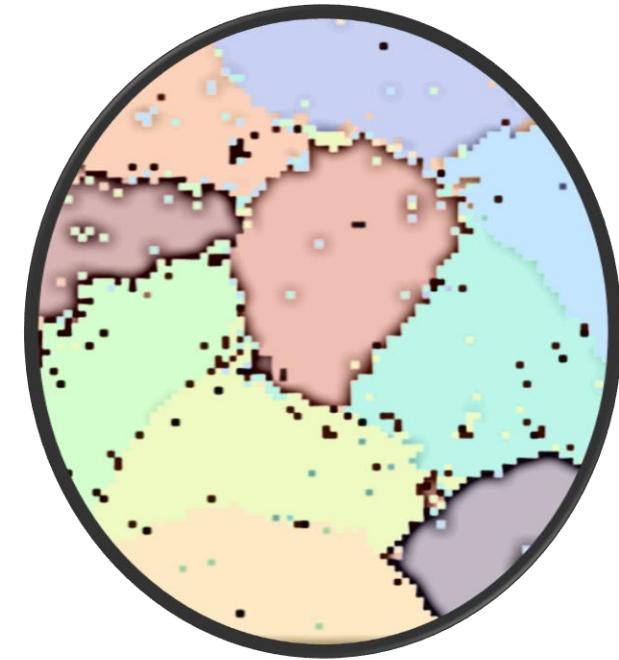
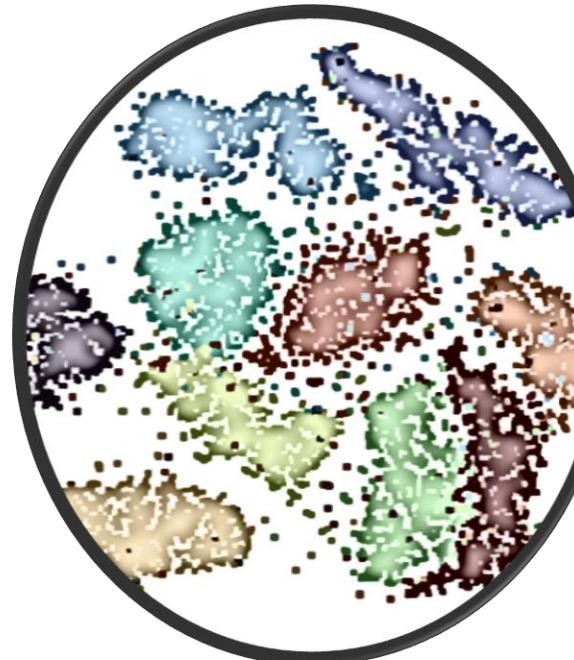
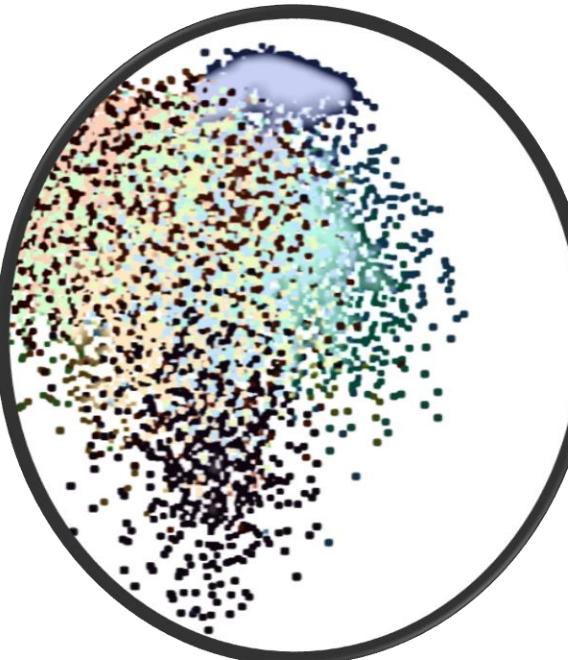


Curse of dimensionality (1)



123

James Hopkins, 123



Void-Vis Vs
Compact-Vis

Dimensionality reduction $\mathbb{R}^n \rightarrow \mathbb{R}^2$

Linear :

- Orthogonal projection

- PCA

- ...

Non linear

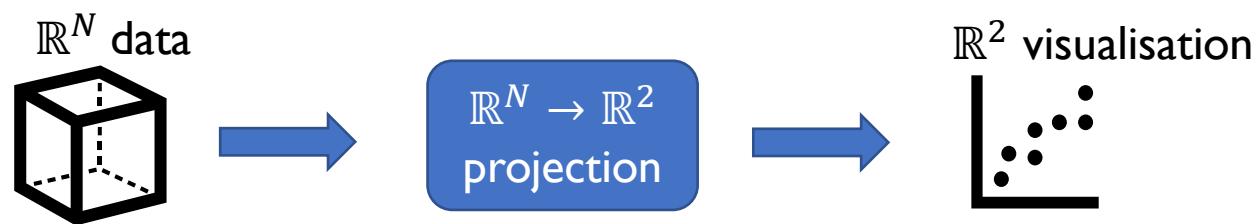
- Multi dimensional scaling

- Graph-based kernel

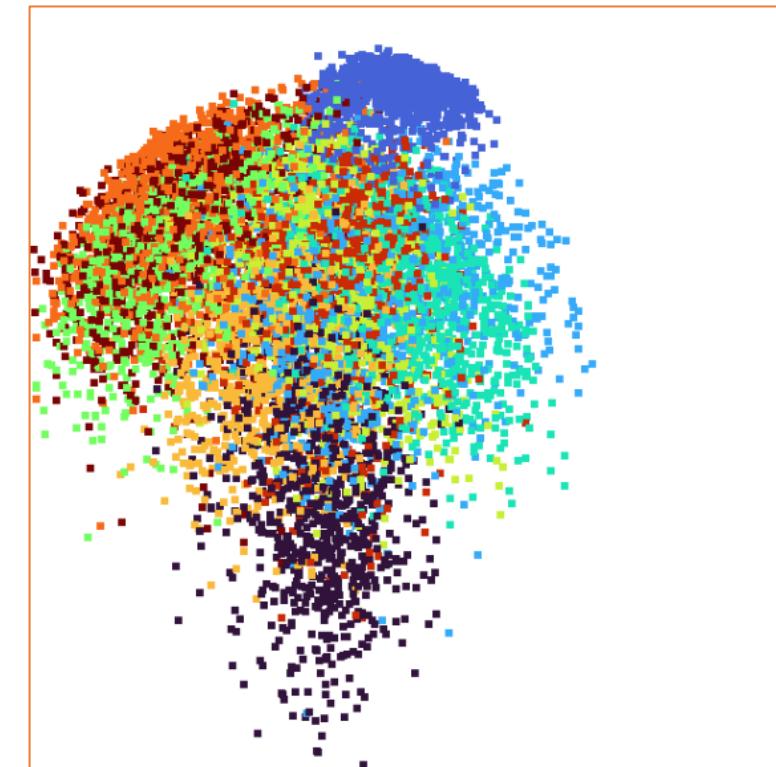
- T-Sne

- Autoencoder

- ...



3	4	2	1	9	5	6	2	1	8
8	9	1	2	5	0	0	6	4	
6	7	0	1	6	3	6	3	7	0
3	7	7	9	4	6	6	1	8	2
2	9	3	4	3	9	8	7	2	5
1	5	9	8	3	6	5	7	2	3
9	3	1	9	1	5	8	0	8	4
5	6	2	6	8	5	8	8	9	9
3	7	7	0	9	4	8	5	4	3
7	9	6	4	7	0	6	9	2	3



Dimensionality reduction $\mathbb{R}^n \rightarrow \mathbb{R}^2$

Linear :

- Orthogonal projection

- PCA

- ...

Non linear

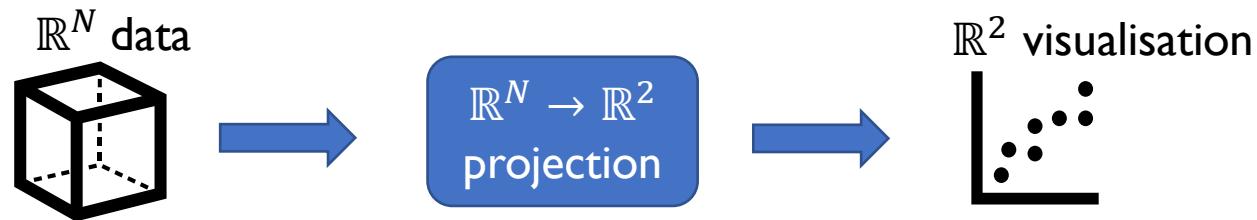
- Multi dimensional scaling

- Graph-based kernel

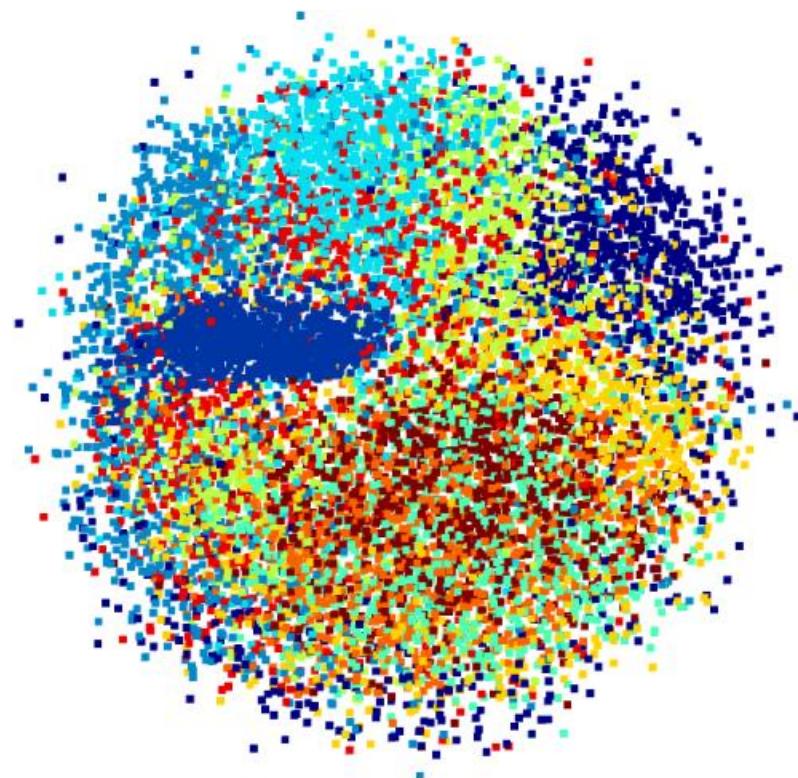
- T-Sne

- Autoencoder

- ...



3	4	2	1	9	5	6	2	1	8
8	9	1	2	5	0	0	6	6	4
6	7	0	1	6	3	6	3	7	0
3	7	7	9	4	6	6	1	8	2
2	9	3	4	3	9	8	7	2	5
1	5	9	8	3	6	5	7	2	3
9	3	1	9	1	5	8	0	8	4
5	6	2	6	8	5	8	8	9	9
3	7	7	0	9	4	8	5	4	3
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Dimensionality reduction $\mathbb{R}^n \rightarrow \mathbb{R}^2$

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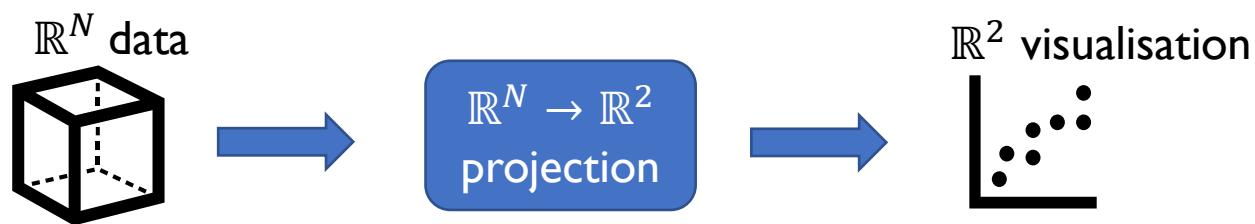
Non linear

- Multi dimensional scaling

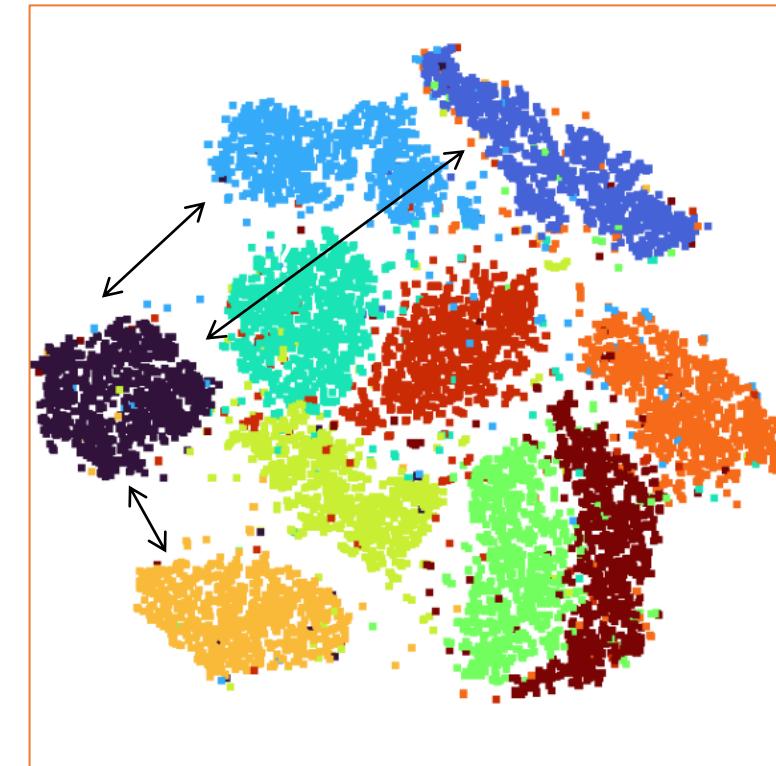
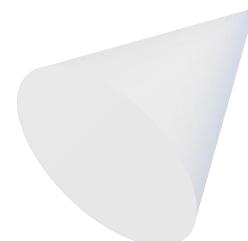
- Graph-based kernel

- Tsne

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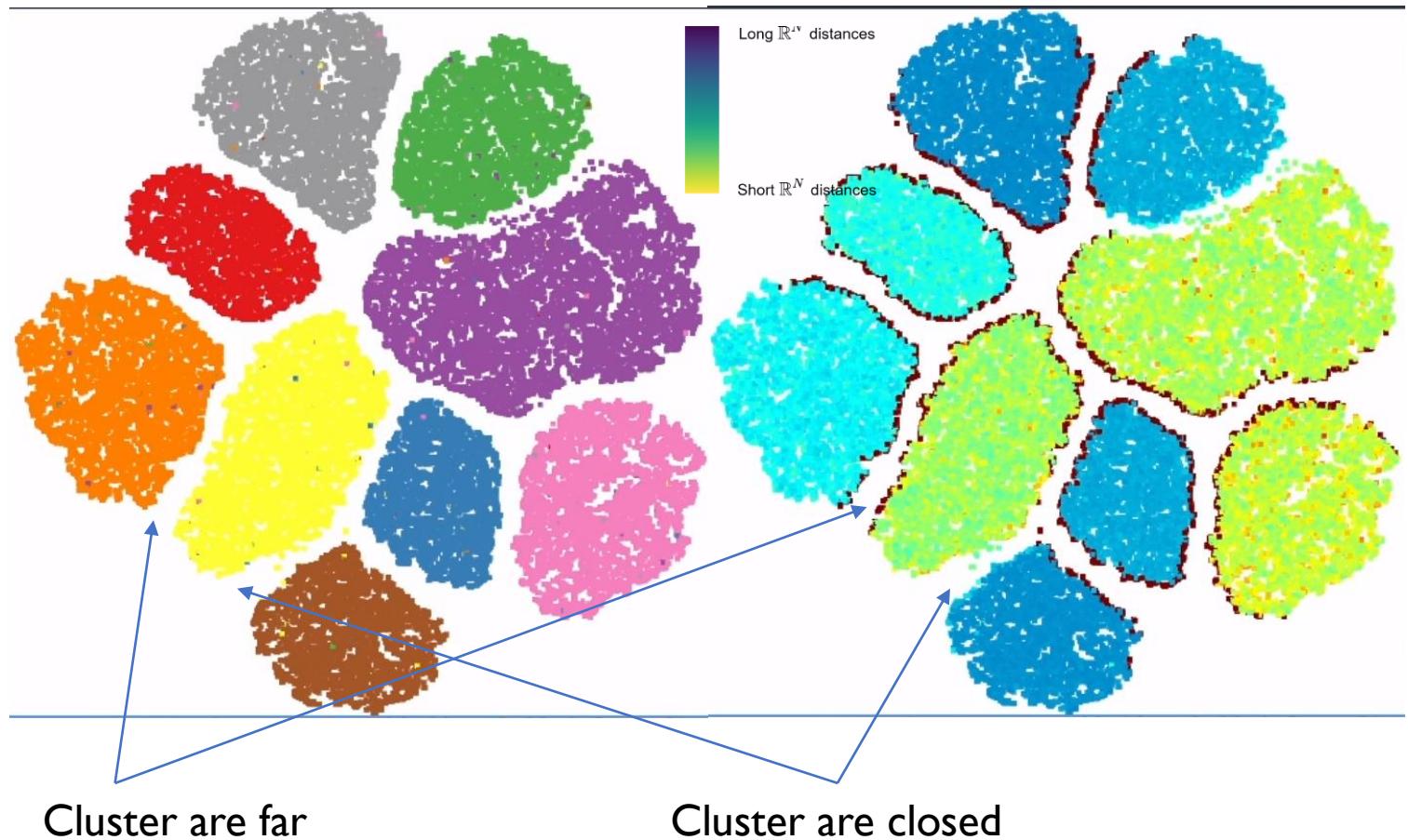


3	4	2	1	9	5	6	2	1	8
8	9	1	2	5	0	0	6	4	
6	7	0	1	6	3	6	3	7	0
3	7	7	9	4	6	6	1	8	2
2	9	3	4	3	9	8	7	2	5
1	5	9	8	3	6	5	7	2	3
9	3	1	9	1	5	8	0	8	4
5	6	2	6	8	5	8	8	9	9
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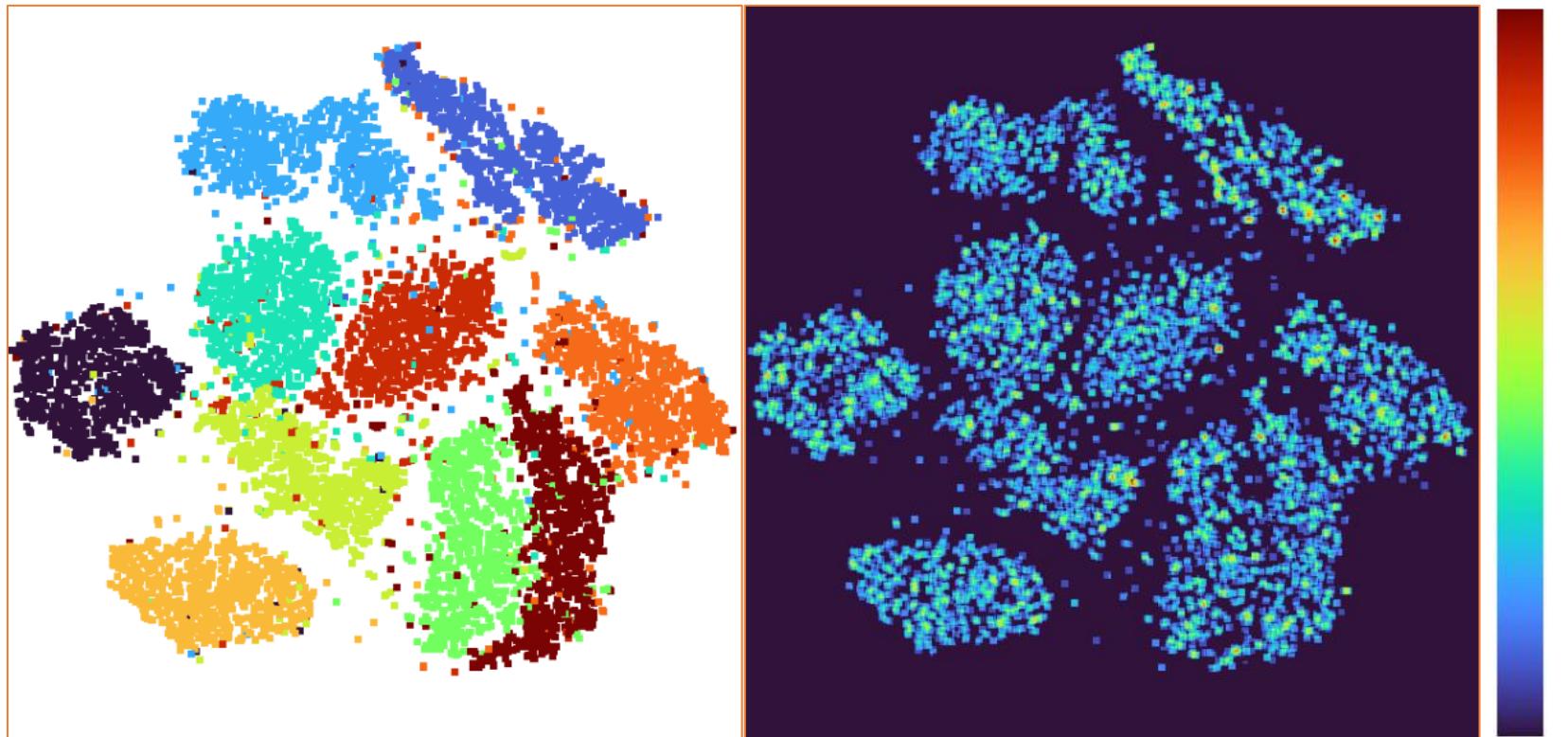
Void visualisation is misleading

- ~~Read values of data points ?~~
- ~~Compare data points to each other ?~~ neighbours
- ~~Estimate density or distribution ?~~
- ~~Find outliers ?~~
- ~~Find clusters of data points ?~~
- ~~Compare clusters to each other ?~~
- ~~Make assumptions ?~~
- ~~Make decisions ?~~



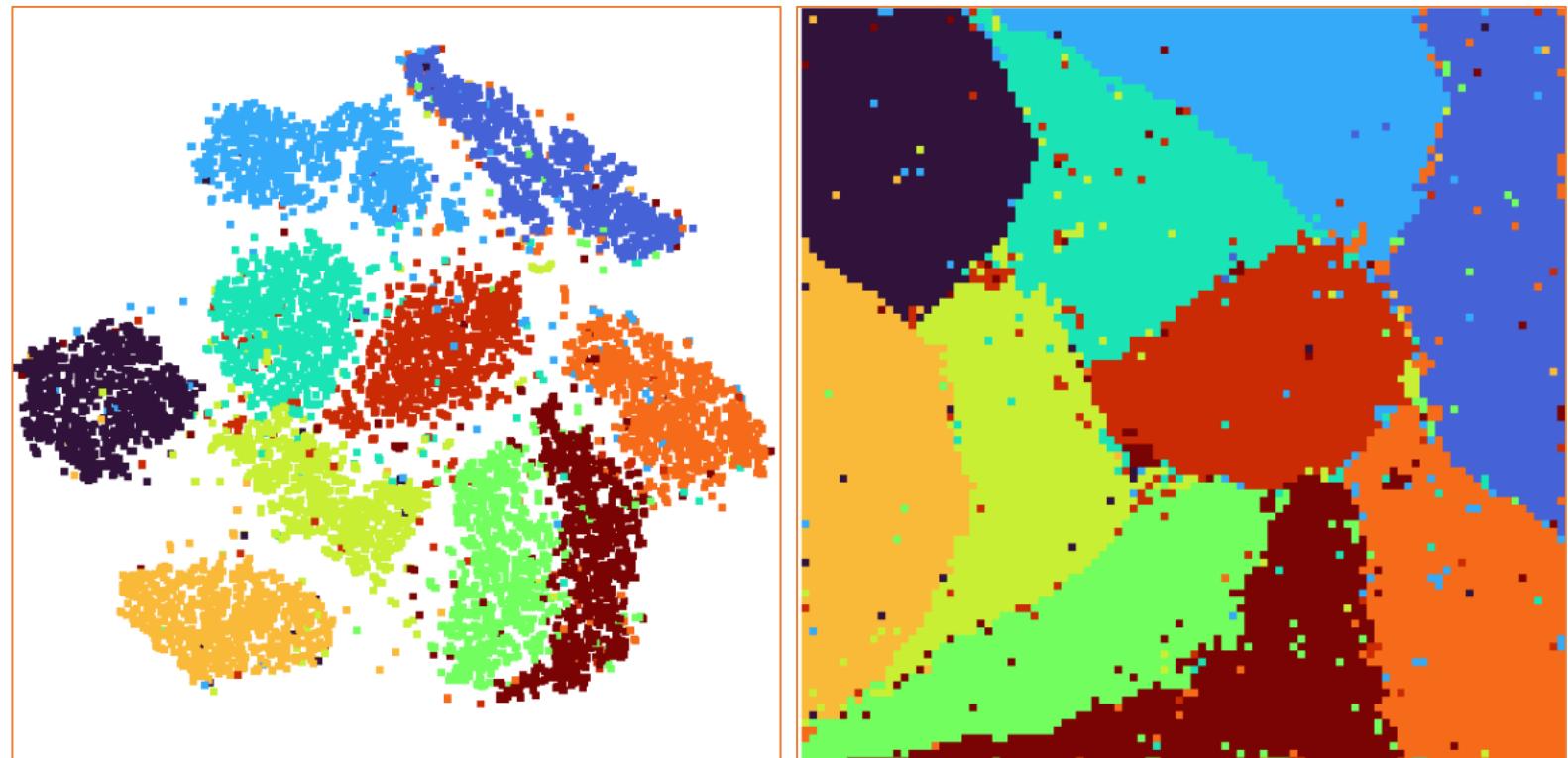
Void visualisation creates cluttering

- ~~Read values of data points ?~~
- ~~Compare data points to each other ?~~ neighbours
- ~~Estimate density or distribution ?~~
- ~~Find outliers ?~~
- ~~Find clusters of data points ?~~
- ~~Compare clusters to each other ?~~
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- ~~Make decisions ?~~



Void-Vis Vs Compact-Vis

- ~~Read values of data points ?~~
- Compare data points ~~to each other~~ ? ~~neighboors~~
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- ~~Make decisions ?~~

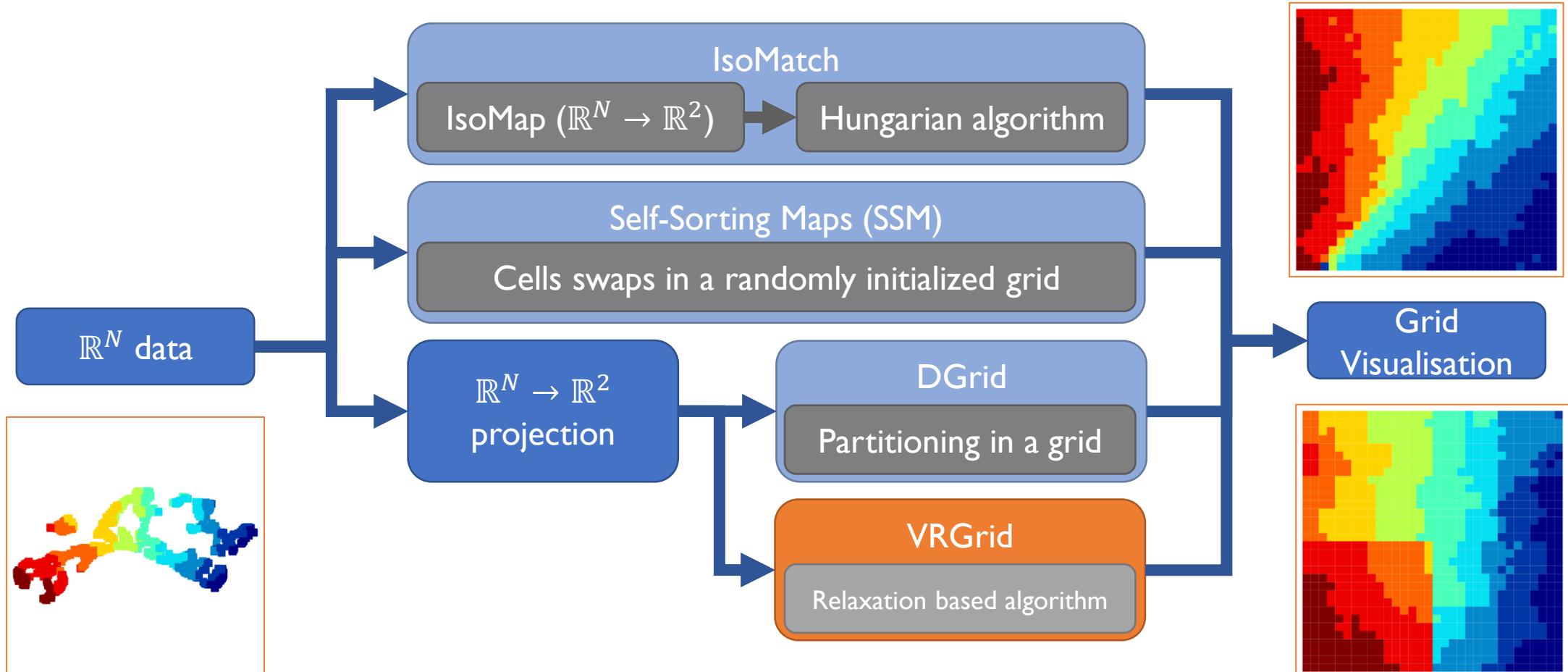


Data points & void visualisation

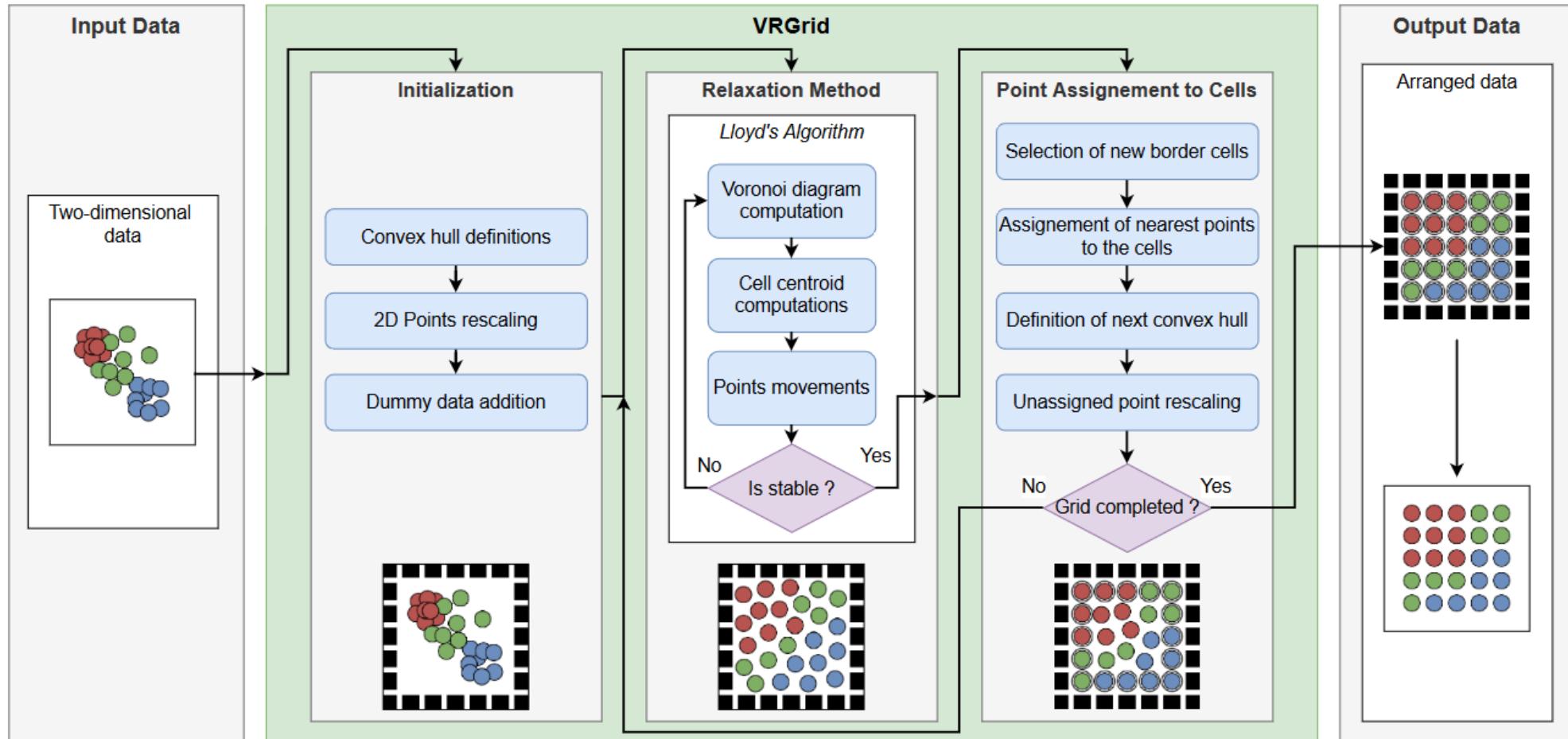
Data points visualisation

How to transform void to non void vis

Grid arrangement methods



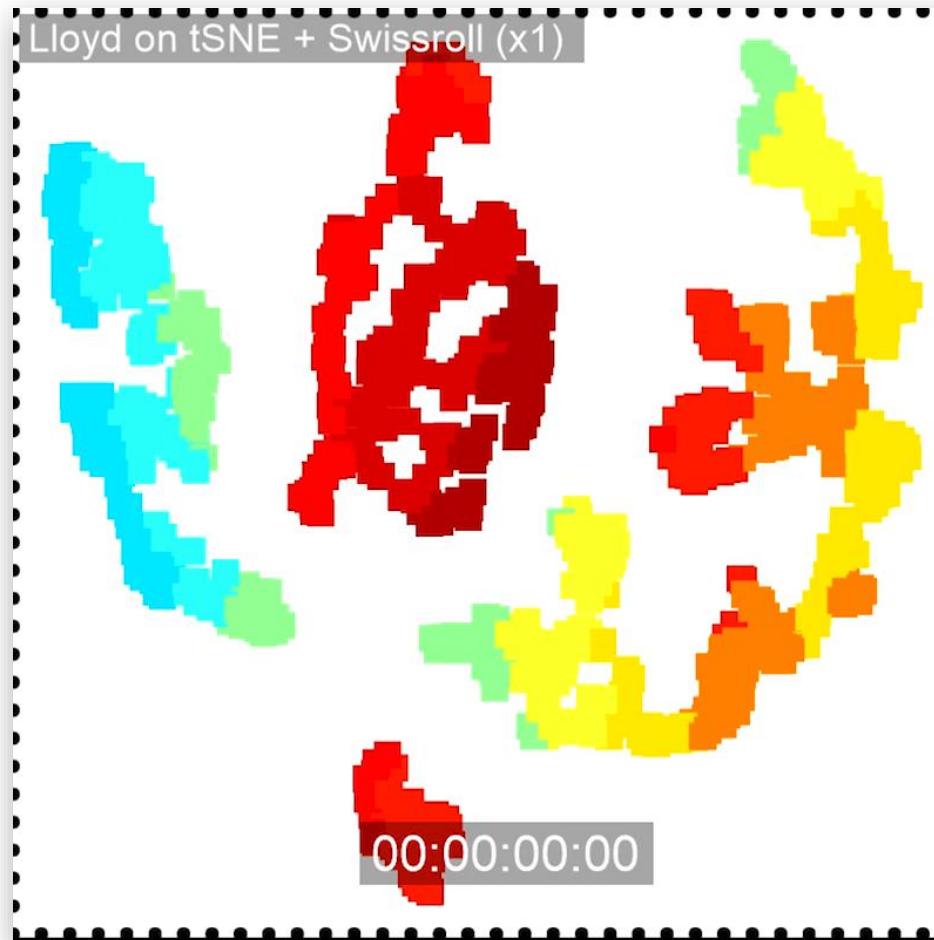
VRGrid presentation



$$O(\sqrt{n} \cdot i \cdot n \cdot \log(n)) = O\left(i \cdot n^{\frac{3}{2}} \cdot \log(n)\right)$$



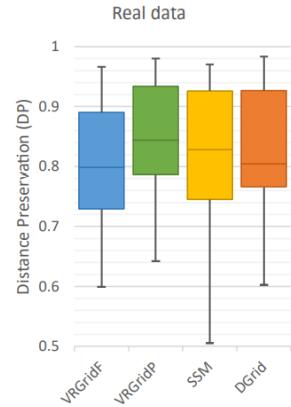
Until all points are affected to a cell



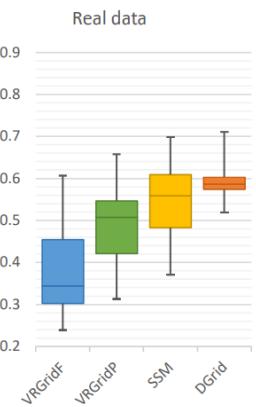
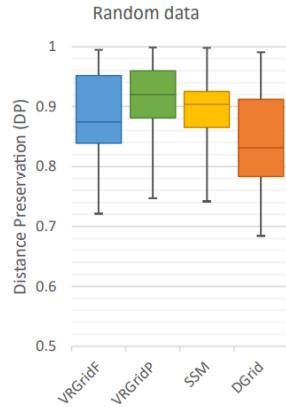
Results

Higher is better

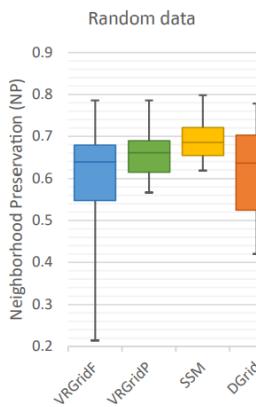
Lower is better



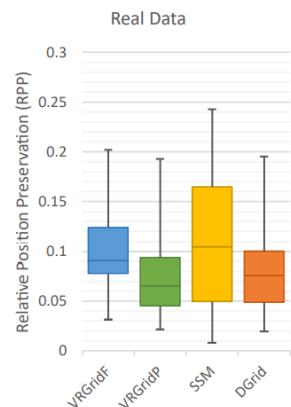
(a) Distance Preservation measure.



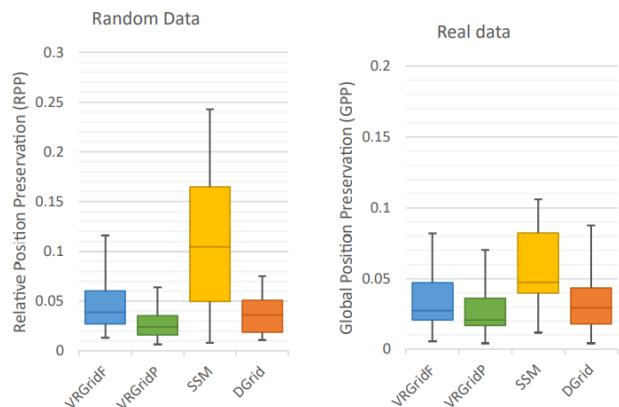
(b) Neighborhood Preservation measure.



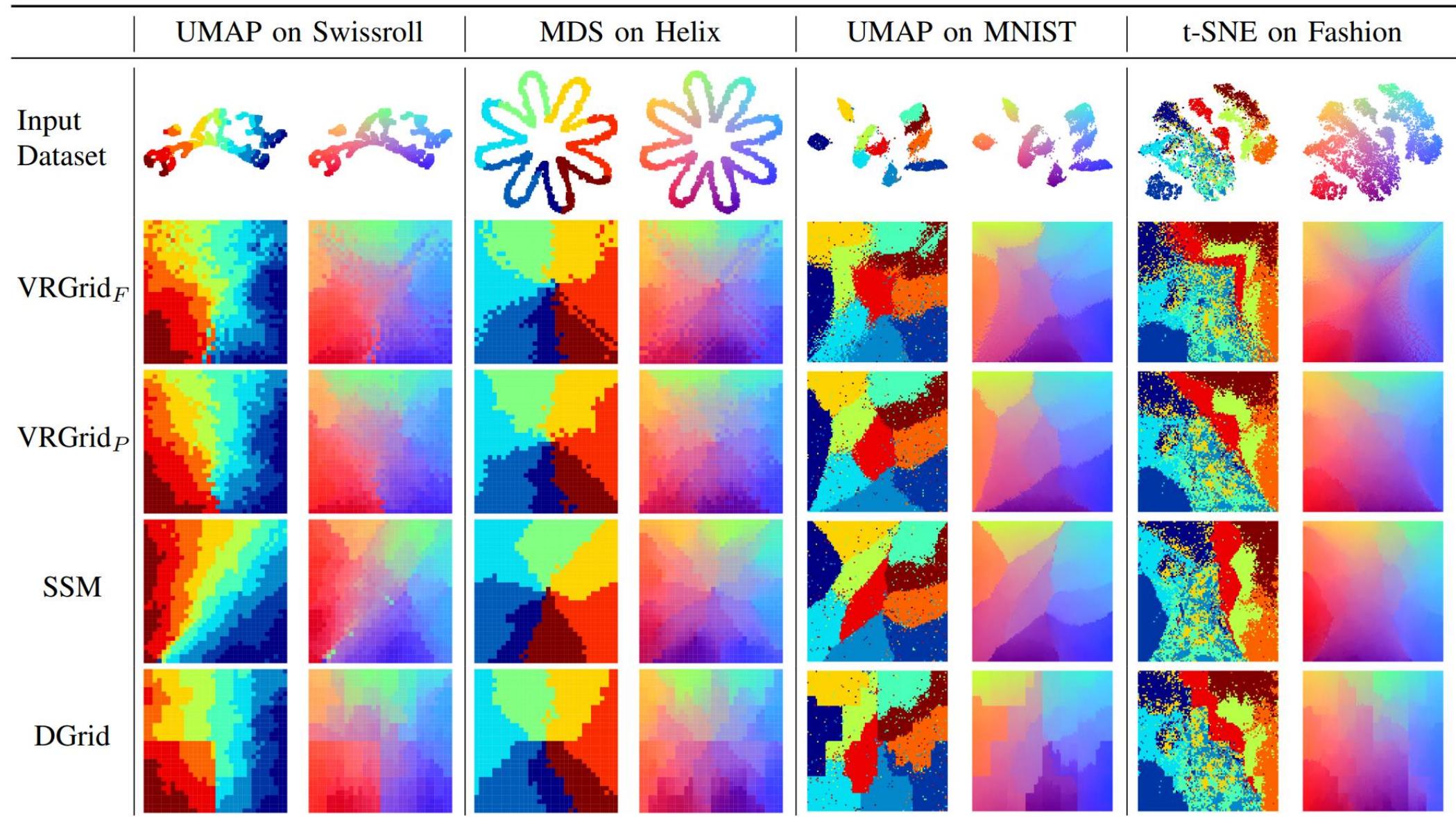
- VRGridP has the best results in all categories except Neighborhood Preservation
- VRGridF's fast approach has a high cost on quality
- DGrid has relatively good results despite the visually strong distortions (\rightarrow wrong metrics ?)
- SSM has bad* results on preservation of positions.
- However, VRGridP and VRGridF are both significantly slower than SSM and DGrid on computation time.



(c) Relative Position Preservation measures.

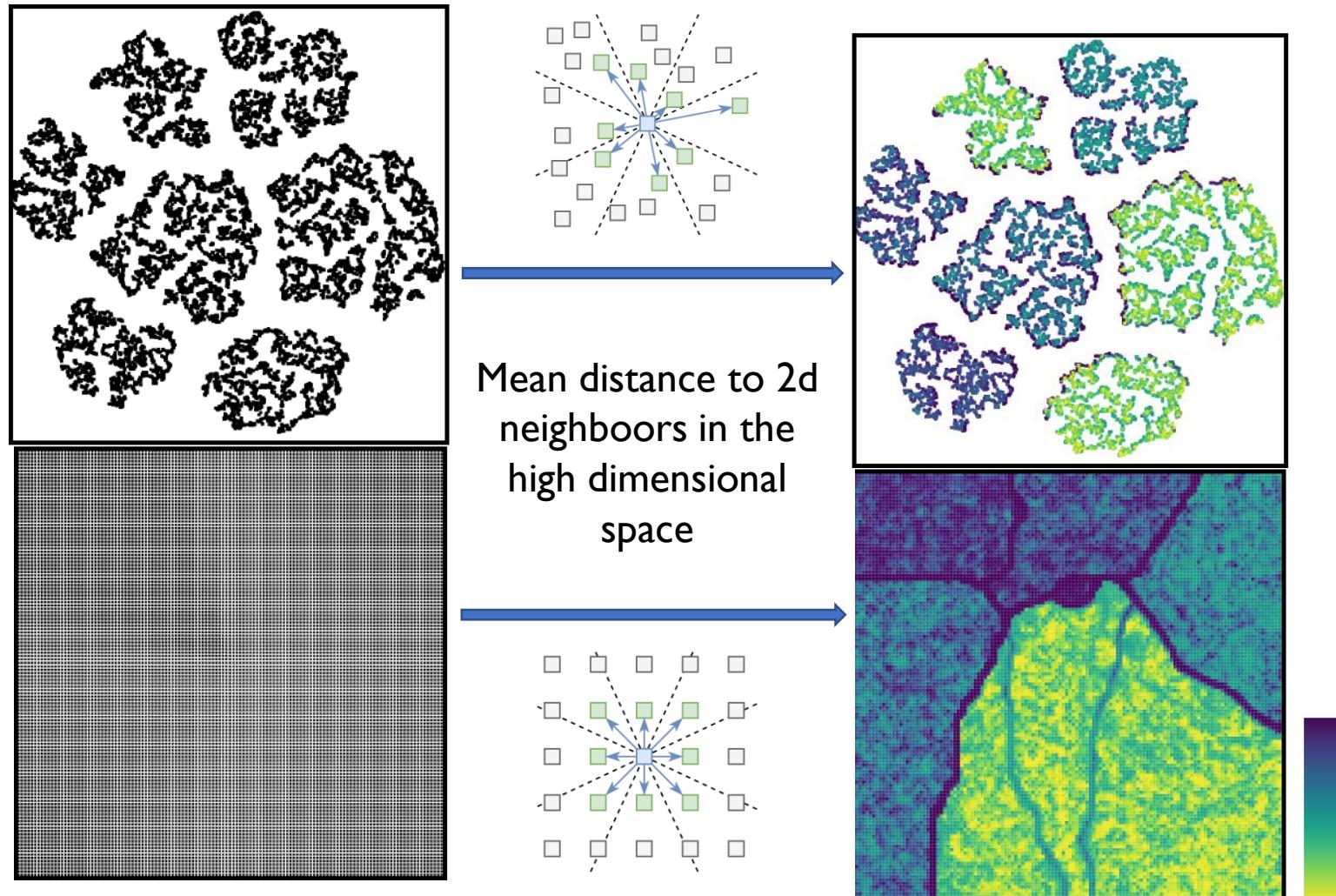


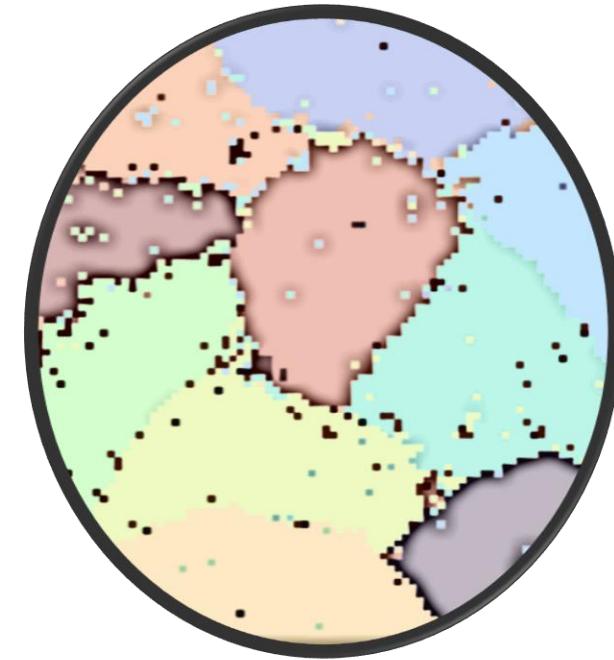
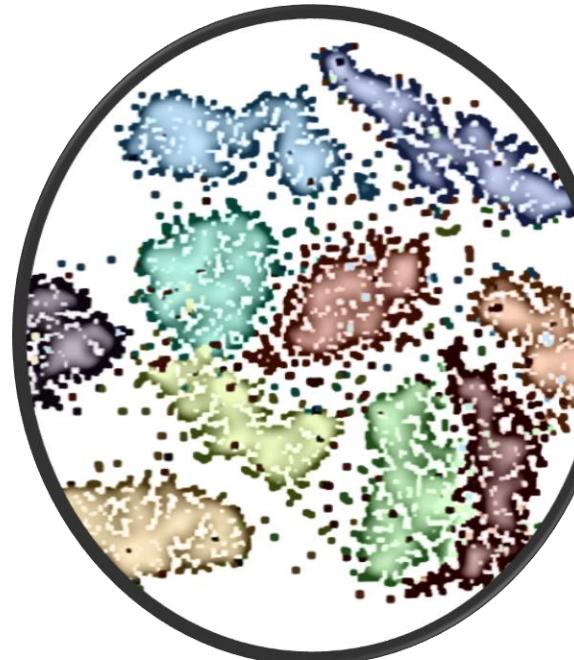
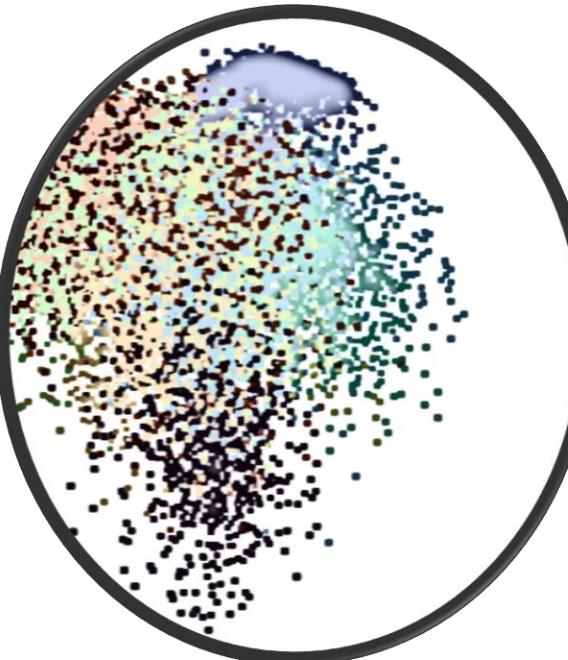
(d) Global Position Preservation measure.



Void-Vis Vs Compact-Vis

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- **Find clusters of data points ?**
- Compare clusters to each other ?
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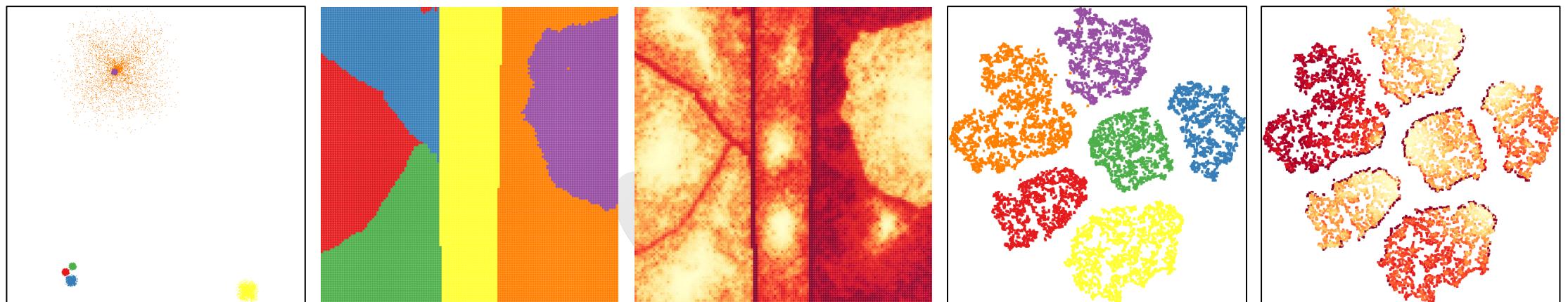
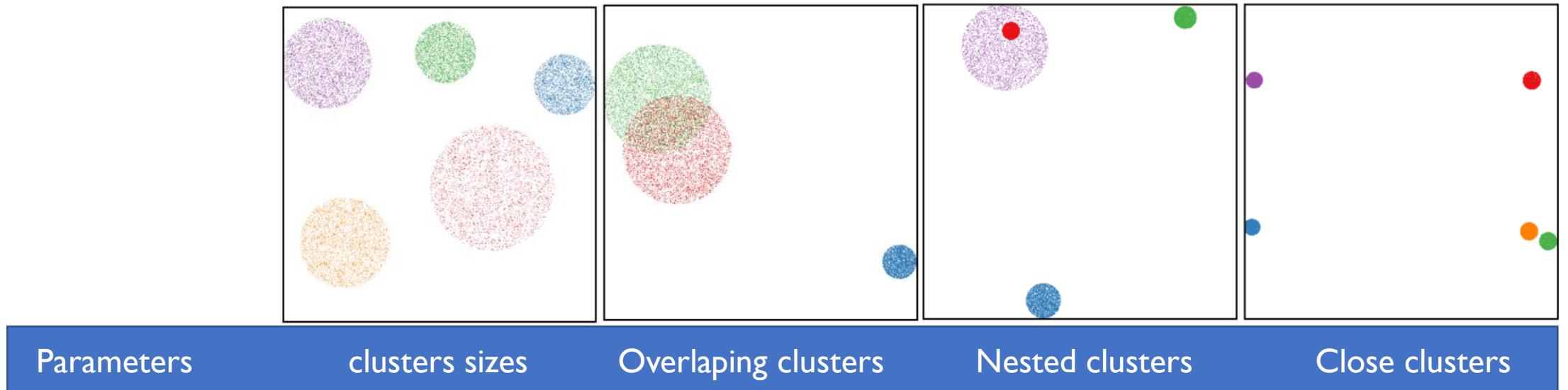




User evaluation

- <https://pivert.labri.fr/eval-en/index.html>

Random generation of dataset



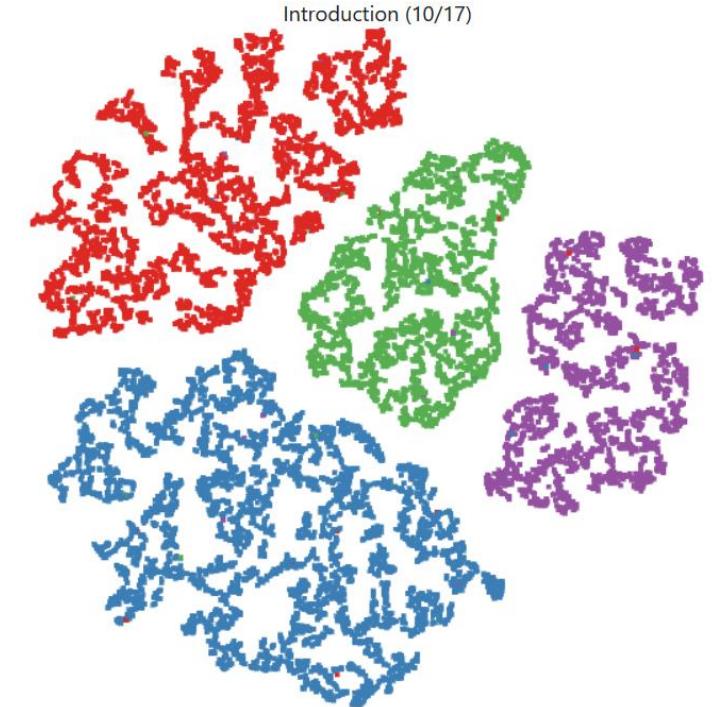
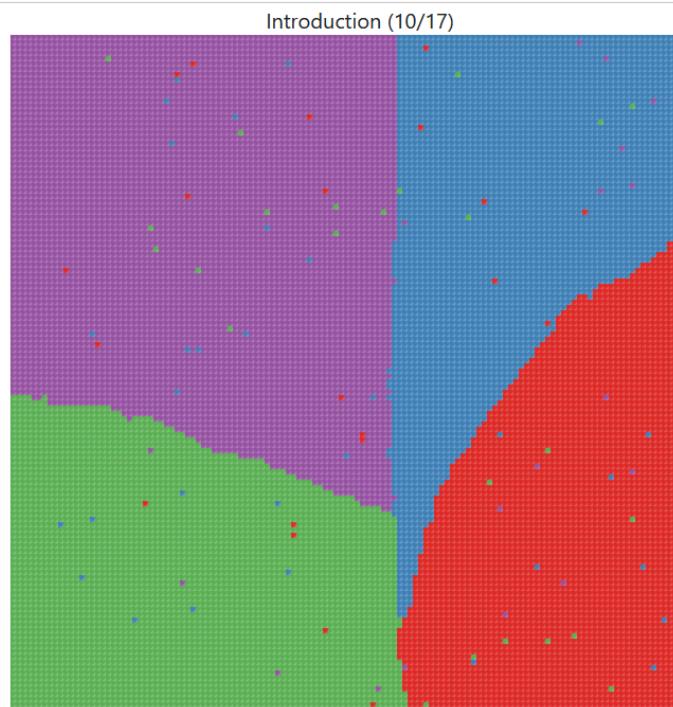
User tasks

Find largest group

Find closest group

Find number of outliers

Find the type of topological structure



User tasks

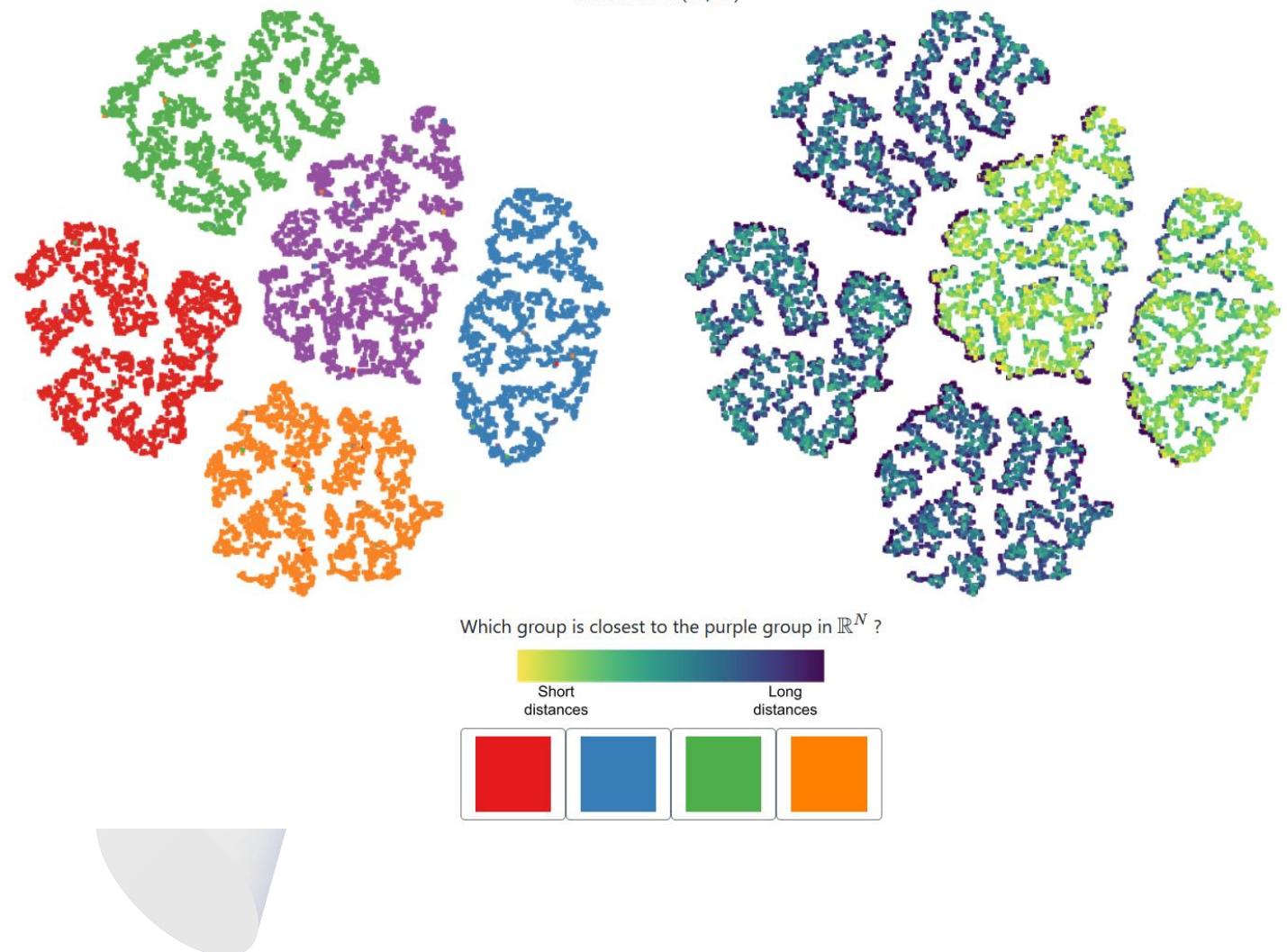
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Introduction (12/17)



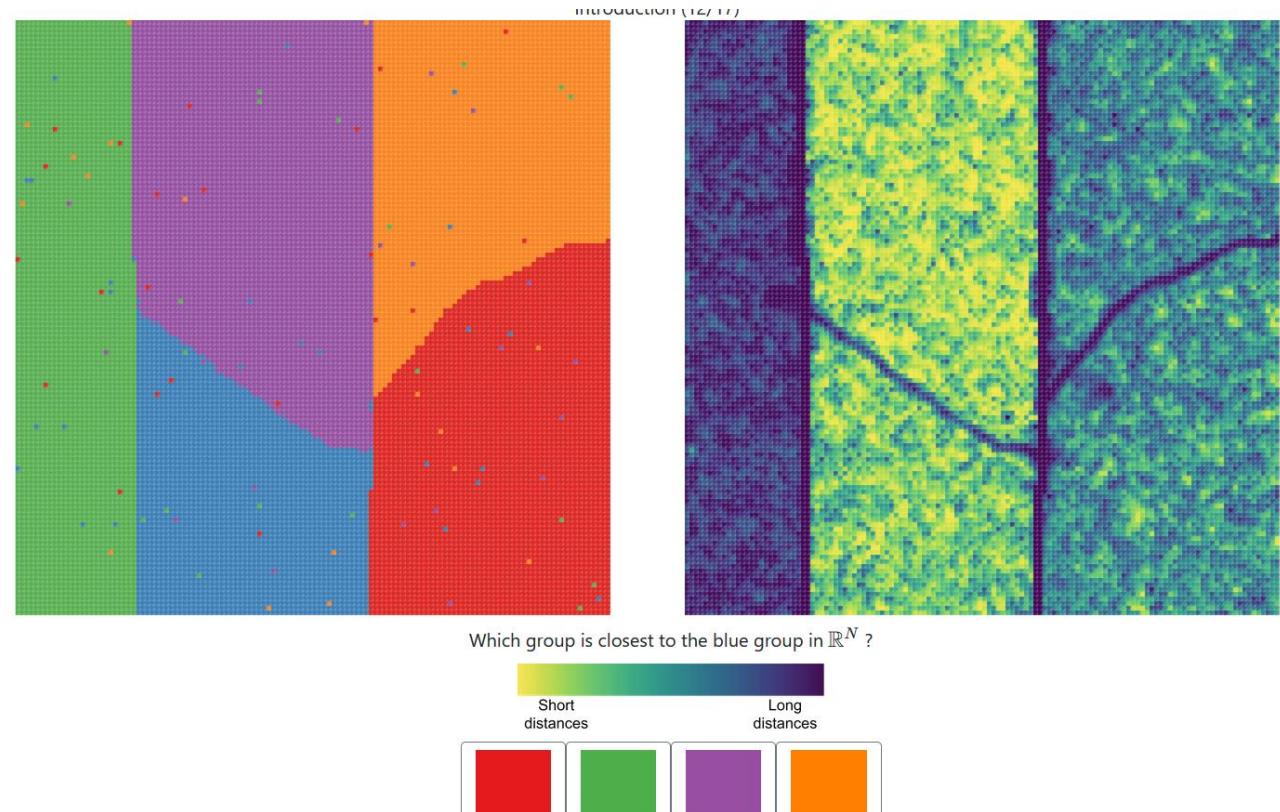
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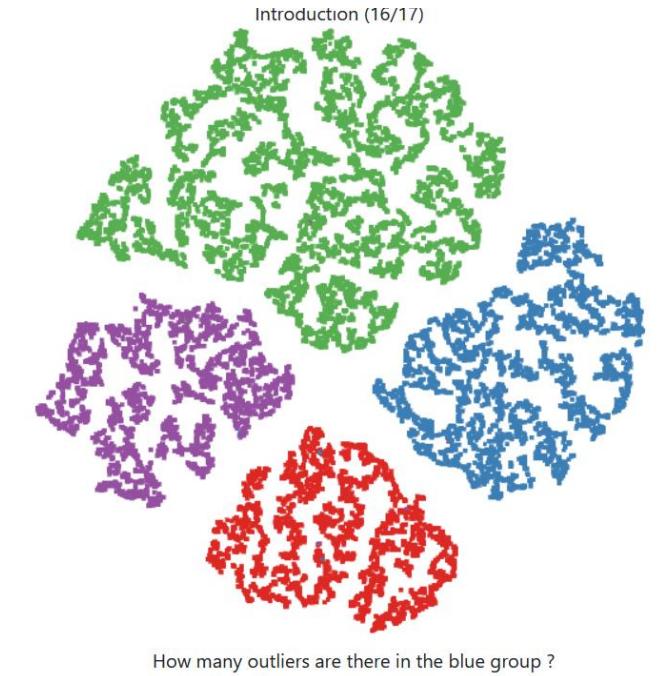
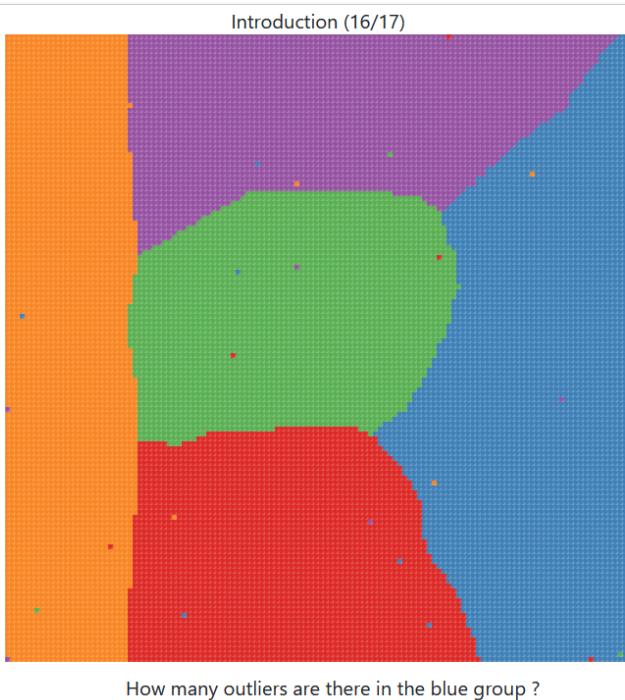
User tasks

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User tasks

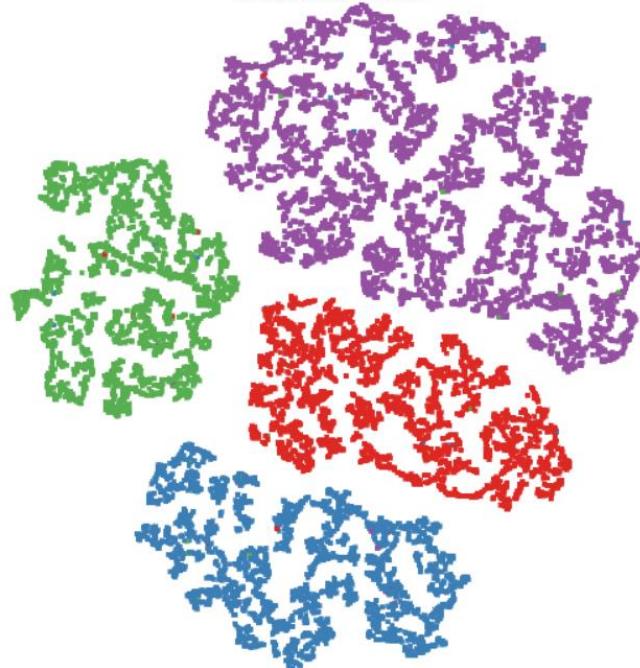
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Find closest group

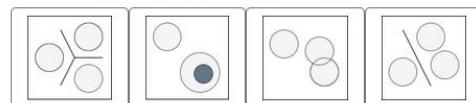
Find number of outliers

Find the type of topological structure

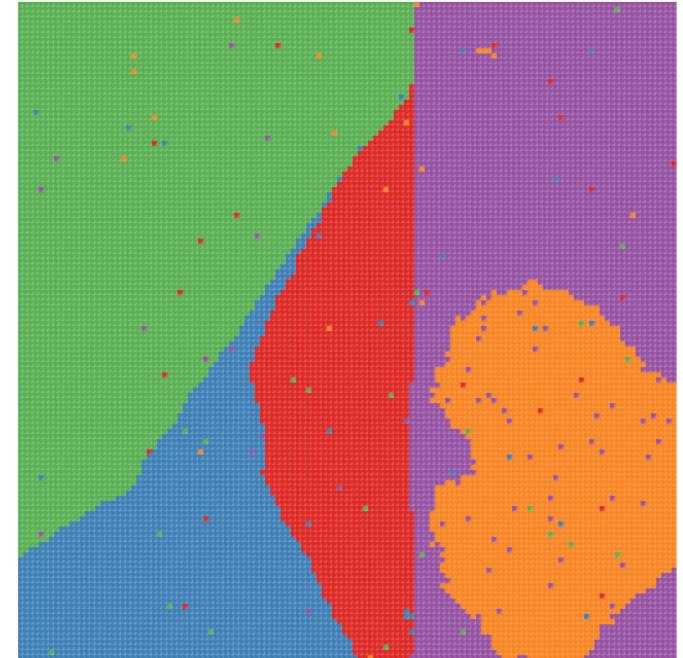
Introduction (14/17)



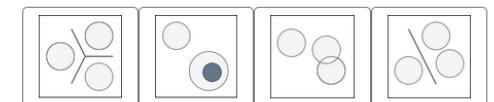
What is the data topology in \mathbb{R}^N ?



Introduction (14/17)



What is the data topology in \mathbb{R}^N ?



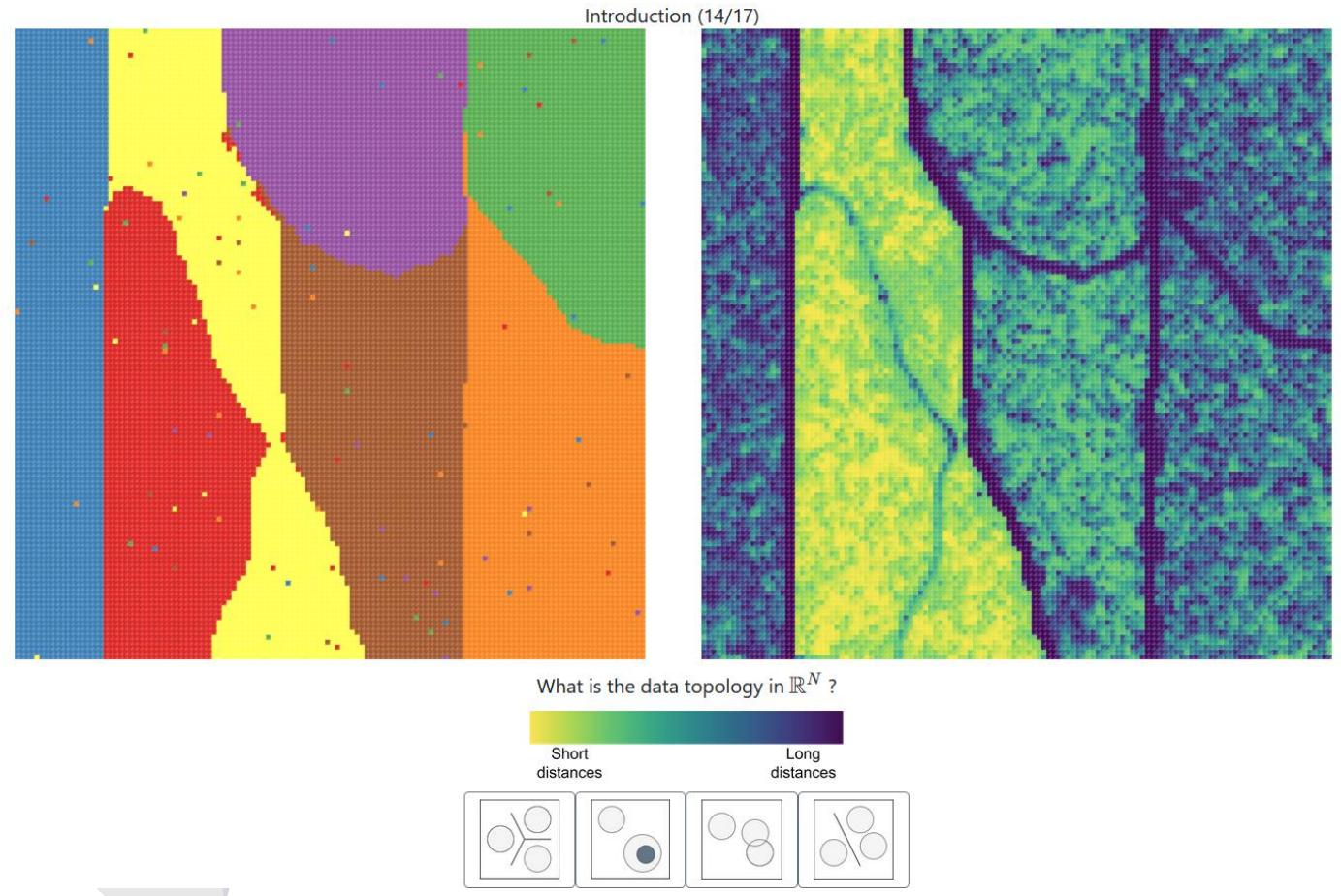
User tasks

Find largest group

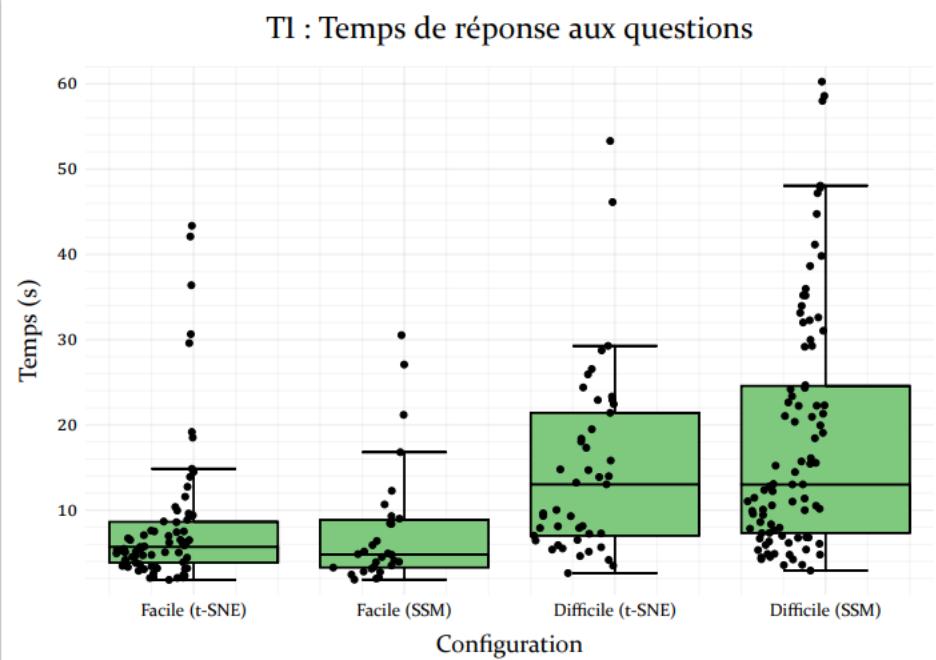
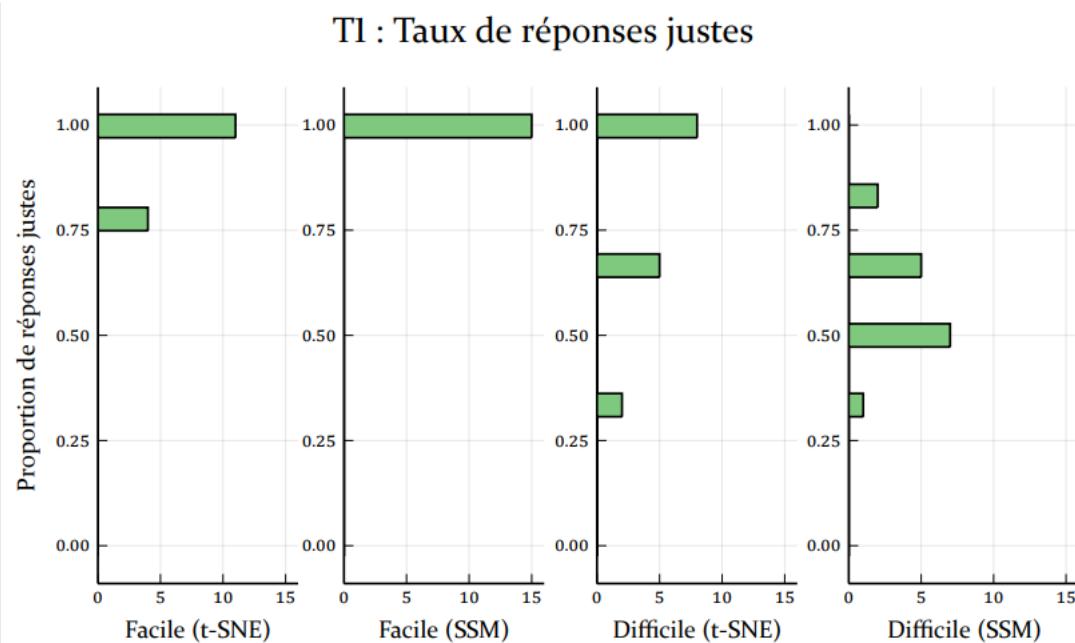
Find closest group

Find number of outliers

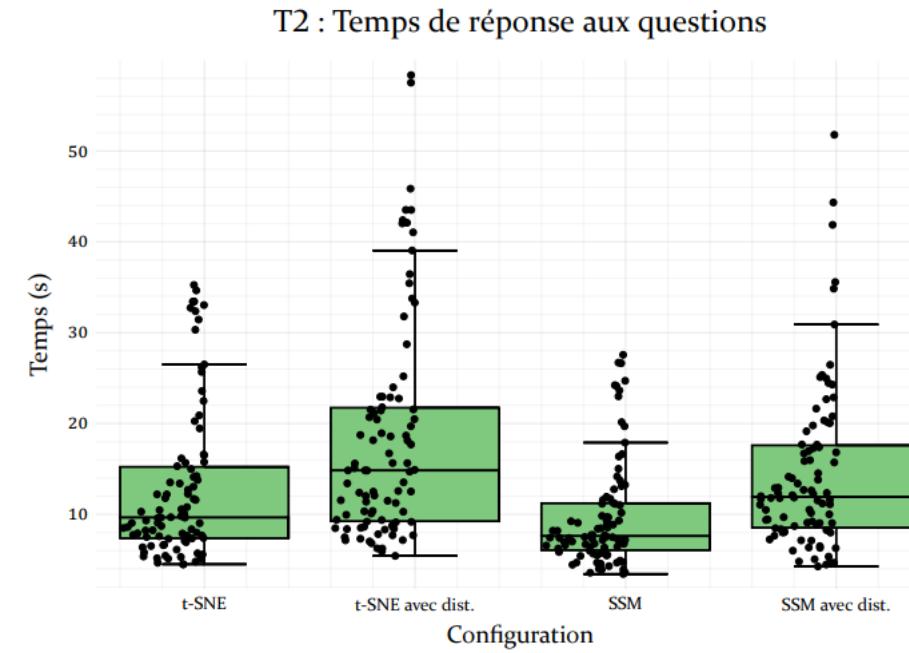
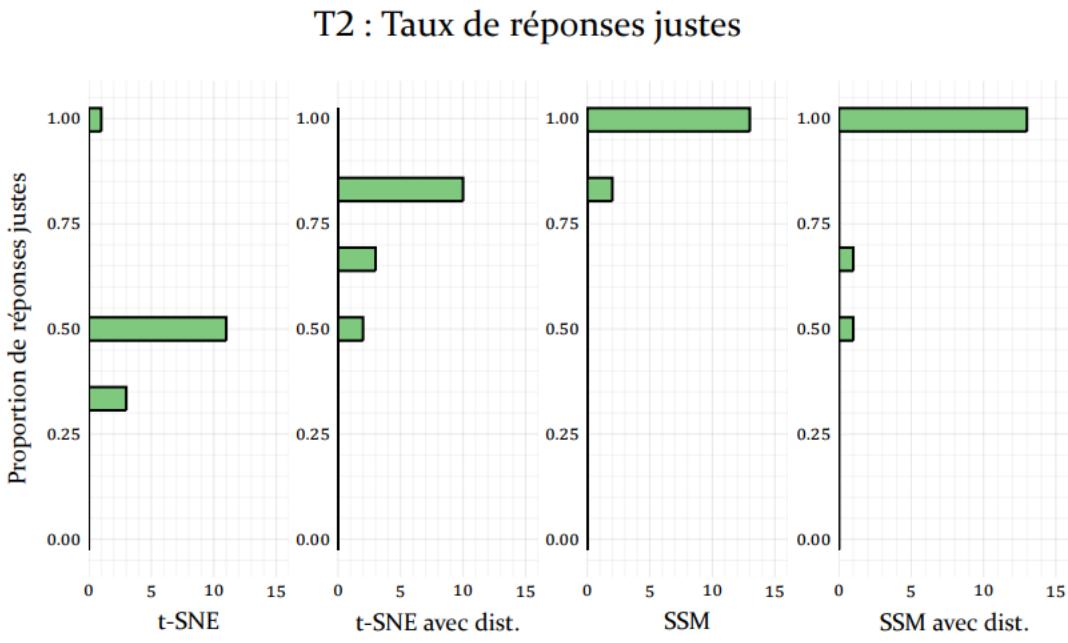
Find the type of topological structure



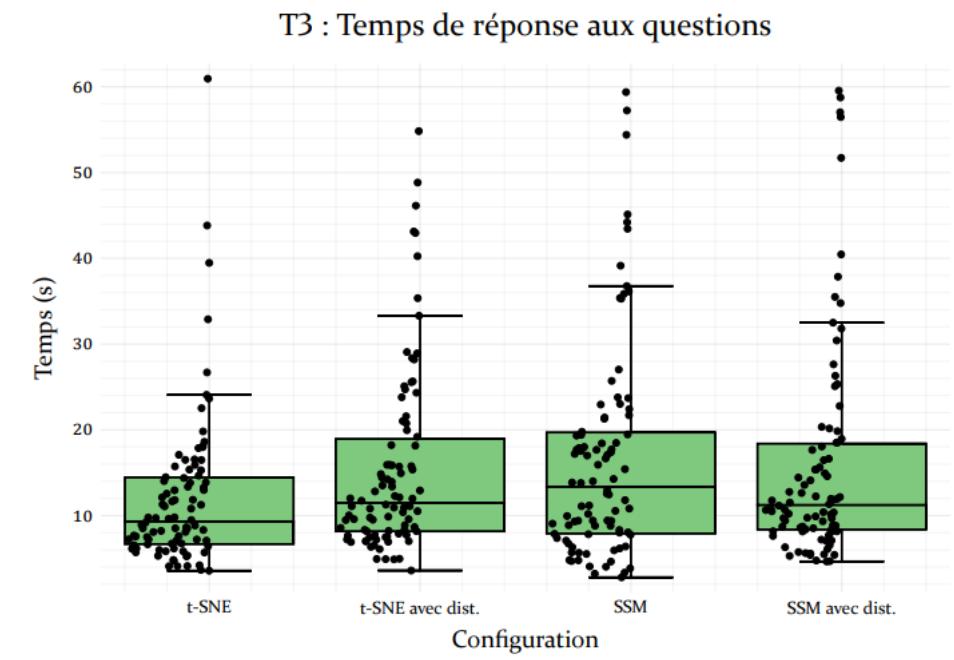
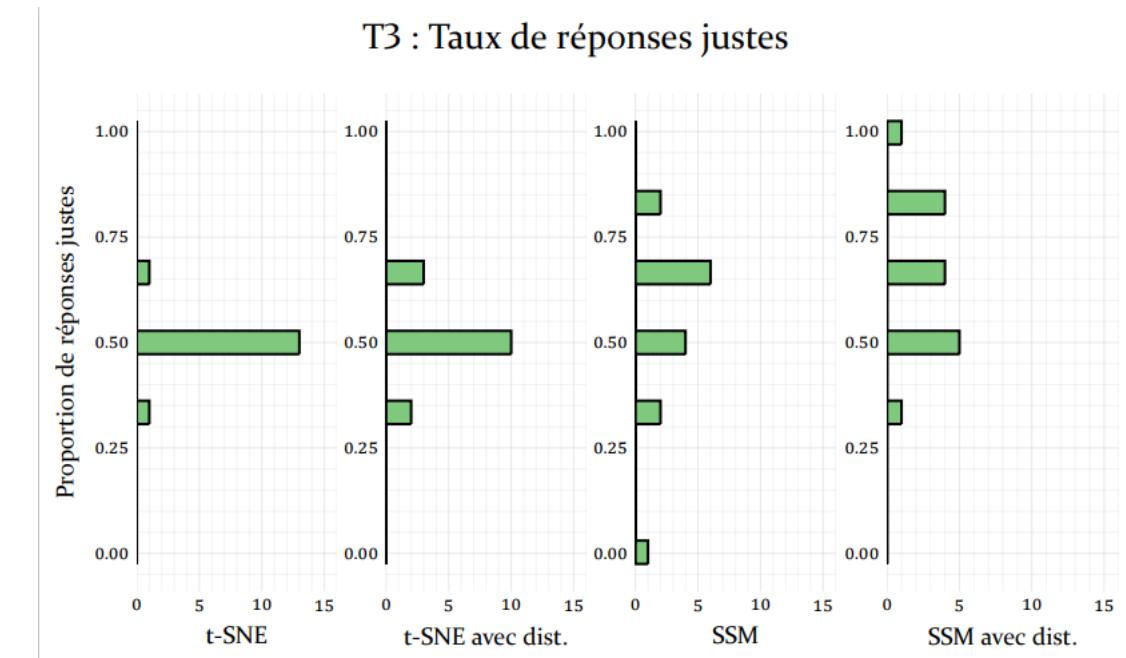
Find larger group



Find closest group

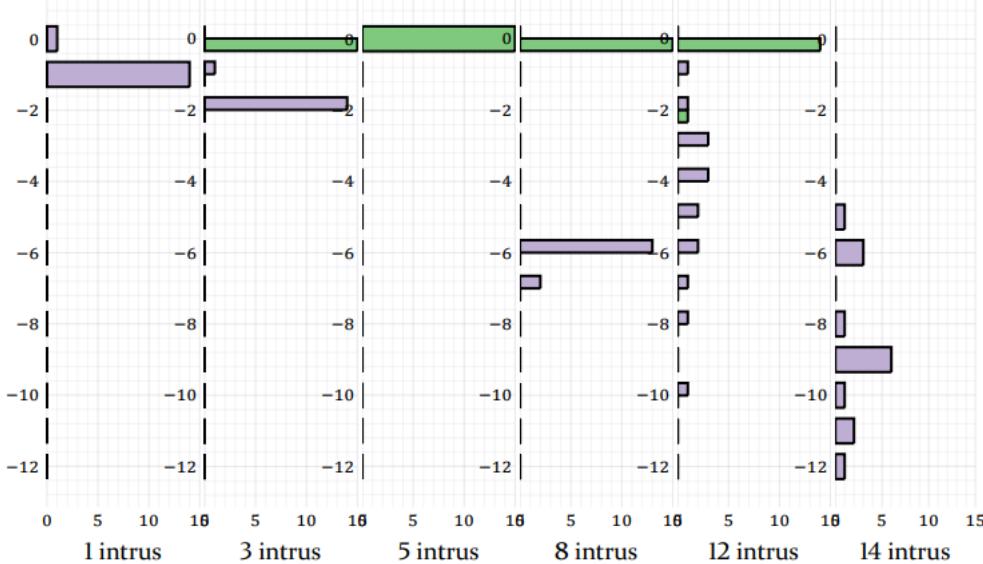


Find the type of topological structure

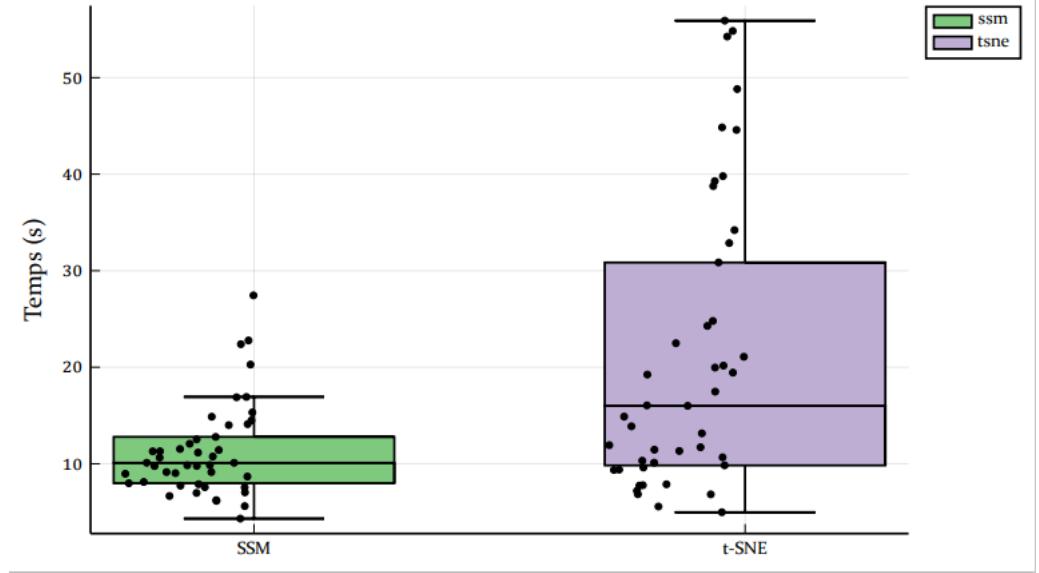


Find number of outliers

Ecart des réponses par rapport à la vérité



T4 : Temps de réponse aux questions



Future work InvolvD

- Intégrer la méthode dans notre prototype
- Evaluer l'impact

